### 8.022 (E\&M) - Lecture 13

## Topics:

- B's role in Maxwell's equations
- Vector potential
- Biot-Savart law and its applications


## What we learned about magnetism so far...

- Magnetic Field B
- Experiments: currents in wires generate forces on charges in motion
- Force exerted on charge $q$ with velocity v: $\vec{F}=q \frac{\vec{v}}{c} \times \vec{B}$
- Explanation: there must exist a magnetic field $B$
- Special Relativity: B is just E seen from another reference frame...
- Ampere's Law: $\oint_{C} \vec{B} \cdot d \vec{s}=\frac{4 \pi}{c} I_{\text {encl }}$
- Application: B generated by current in a wire: $\vec{B}=\frac{2 I}{c r} \hat{\varphi}$


## Divergence of $B$

- Consider the B produced by a wire of current: $\vec{B}=\frac{2 I}{c r} \hat{\varphi}$
- Calculate its divergence in Cartesian coordinates:

Given $r=\sqrt{x^{2}+y^{2}}$ and $\hat{\varphi}=\hat{y} \cos \varphi-\hat{x} \sin \varphi=\frac{x \hat{y}}{\sqrt{x^{2}+y^{2}}}-\frac{y \hat{x}}{\sqrt{x^{2}+y^{2}}} \Rightarrow$
$\vec{B}=\frac{2 I}{c r}\left(\frac{x \hat{y}}{x^{2}+y^{2}}-\frac{y \hat{x}}{x^{2}+y^{2}}\right) \Rightarrow \vec{\nabla} \cdot \vec{B}=\frac{2 I}{c r}\left(\frac{2 y x}{\left(x^{2}+y^{2}\right)^{2}}-\frac{2 x y}{\left(x^{2}+y^{2}\right)^{2}}\right)=0$

- This is a general property of the magnetic field: $\vec{\nabla} \cdot \vec{B}=0$
- Similar equation for $\mathrm{E}: \vec{\nabla} \cdot \vec{E}=4 \pi \rho$
- The divergence of $E$ is related to the density of electric charges
- The divergence of $B$ must be related to the density of magnetic charges $\rightarrow$ Magnetic monopole don't exist
(There may be magnetic monopoles leftover from the Early Universe, but never observed experimentally so far)


## Ampere's law in differential form

- Apply Stoke's theorem to Ampere's law:

$$
\begin{aligned}
& \oint_{C} \vec{B} \cdot d \vec{s}=\frac{4 \pi}{c} I_{\text {encl }} \\
& \oint_{C} \vec{B} \cdot d \vec{s}=\int_{S} \vec{\nabla} \times \vec{B} \cdot d \vec{S}=\frac{4 \pi}{c} \int_{S} \vec{J} \cdot d \vec{S} \\
& \int_{S}\left(\vec{\nabla} \times \vec{B}-\frac{4 \pi}{c} \vec{J}\right) \cdot d \vec{S}=0 \text { for any surface }
\end{aligned}
$$

$\rightarrow$ Ampere's law in differential form: $\vec{\nabla} \times \vec{B}=\frac{4 \pi}{c} \vec{J}$

## Toward Maxwell's equations

- Let's collect all the equations in differential form that we found so far:
$\begin{cases}\vec{\nabla} \cdot \vec{E}=4 \pi \rho & \leftarrow \text { Relates E and charge density ( } \rho \text { ) - Gauss } \\ \vec{\nabla} \cdot \vec{B}=0 & \leftarrow \text { No magnetic monopoles! } \\ \vec{\nabla} \times \vec{E}=0 & \leftarrow \mathrm{E} \text { is a conservative field } \\ \vec{\nabla} \times \vec{B}=\frac{4 \pi}{c} \vec{J} & \leftarrow \text { Relates B and its sources (J) - Ampere }\end{cases}$
- Not complete Maxwell's equations yet, but we are getting closer...


## Vector potential A

- Definition of potential for electric field:
- $\phi(P)=$ work needed to move a unit charge from reference to $P$
- Relationship between $\phi$ and $\mathrm{E}: ~ E=-\nabla \phi$
- Hidden advantage:

$$
\text { If } \vec{E}=-\nabla \phi \Rightarrow \nabla \times \vec{E} \equiv 0 \text { because } \nabla \times(\nabla \phi)=0 \forall \phi
$$

- Can we introduce something similar for $B$ ?
- Goal: enforce div B=0
- Since $\vec{\nabla} \cdot \vec{\nabla} \times \vec{f}=0$ for any $\vec{f}$, we define

$$
\vec{B} \equiv \vec{\nabla} \times \vec{A}
$$

- A is called "vector potential" in analogy with $\phi$
- A is not connected to work or energy (but to angular momentum)
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## Non Uniqueness

- Electrostatics: given a charge distribution and boundary conditions $\rightarrow$ potential $\phi$ is uniquely identified
- Magnetism: does it work the same for A? No, there are infinite number of $A$ corresponding to a single $B$
- Example: $\vec{B}=B_{0} \hat{z}$. Find $\overrightarrow{\mathrm{A}}$ that creates this $\overrightarrow{\mathrm{B}}$ field.

> Requirements:

Q: what current creates this B?

$$
\left\{\begin{array} { l } 
{ \mathrm { B } _ { \mathrm { x } } = \frac { \partial \mathrm { A } _ { \mathrm { z } } } { \partial \mathrm { y } } - \frac { \partial \mathrm { A } _ { \mathrm { y } } } { \partial z } = 0 } \\
{ \mathrm { B } _ { \mathrm { y } } = \frac { \partial \mathrm { A } _ { \mathrm { x } } } { \partial z } - \frac { \partial \mathrm { A } _ { \mathrm { z } } } { \partial x } = 0 \Rightarrow \text { Possible solutions: } } \\
{ \mathrm { B } _ { \mathrm { z } } = \frac { \partial \mathrm { A } _ { \mathrm { x } } } { \partial y } - \frac { \partial \mathrm { A } _ { \mathrm { y } } } { \partial x } = B _ { 0 } }
\end{array} \left\{\begin{array}{c}
\vec{A}=-y B_{0} \hat{x} \\
\vec{A}=x B_{0} \hat{y} \\
\vec{A}=\frac{B_{0}}{2}(-y \hat{x}+x \hat{y}) \\
\vec{A}=\ldots \text { infinite others! }
\end{array}\right.\right.
$$

- We are given one "coupon" to simplify equations when needed


## Poisson's equation for A

- Electrostatics:

$$
\left\{\begin{array}{l}
\vec{E}=-\vec{\nabla} \phi \\
\vec{\nabla} \cdot \vec{E}=4 \pi \rho
\end{array} \Rightarrow \nabla^{2} \phi=-4 \pi \rho\right. \text { Poisson's equation }
$$

- Magnetism:
$\left\{\begin{array}{l}\vec{B}=\vec{\nabla} \times \vec{A} \\ \vec{\nabla} \times \vec{B}=\frac{4 \pi}{c} \vec{J}\end{array} \quad \Rightarrow \vec{\nabla} \times \vec{\nabla} \times \vec{A}=\frac{4 \pi}{c} \vec{\jmath} \Rightarrow \vec{\nabla}(\vec{\nabla} \cdot \vec{A})-\nabla^{2} \vec{A}=\frac{4 \pi}{c} \vec{\jmath}\right.$
We used the identity: $\vec{\nabla} \times \vec{\nabla} \times \vec{A}=\vec{\nabla}(\vec{\nabla} \cdot \vec{A})-\nabla^{2} \vec{A} \quad$ (Pset\#7)
- Use your coupon now!

$$
\text { Choosing } \vec{\nabla} \cdot \vec{A}=0 \Rightarrow \nabla^{2} \vec{A}=-\frac{4 \pi}{C} \vec{J}
$$

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## Solving Poisson's equation for A

How do you solve $\nabla^{2} \vec{A}=-\frac{4 \pi}{c} \vec{J}$ ?
Think of it in cartesian coordinates: $\left\{\begin{array}{l}\nabla^{2} A_{x}=-\frac{4 \pi}{c} J_{x} \\ \nabla^{2} A_{y}=-\frac{4 \pi}{c} J_{y} \\ \nabla^{2} A_{z}=-\frac{4 \pi}{c} J_{z}\end{array}\right.$
Remember Poisson's equation $\nabla^{2} \phi=-4 \pi \rho$ and its solution $\phi=\int_{V} \frac{\rho}{r} d V$
Same as our new equation if replace $\phi \rightarrow \overrightarrow{\mathrm{A}}$ and $\rho \rightarrow \frac{\vec{\jmath}}{c} \Rightarrow \vec{A}=\frac{1}{c} \int_{V} \frac{\vec{\jmath}}{r} d V$
For current flowing in a wire: $\vec{A}=\frac{l}{C} \int_{\text {wire }} \frac{d \vec{l}}{r}$

## Biot-Savart Law

Find $\vec{B}$ produced from current knowing that $\vec{A}=\frac{l}{c} \int_{\text {wire }} \frac{d \vec{l}}{r}$.
$\overrightarrow{\mathrm{B}}=\vec{\nabla} \times \overrightarrow{\mathrm{A}}=\vec{\nabla} \times \frac{l}{c} \int_{\text {wire }} \frac{d \vec{l}}{r}=\frac{l}{c} \int_{\text {wire }} \vec{\nabla} \times \frac{d \vec{l}}{r}$
Using the fact that $\nabla \times(\mathrm{ab})=\mathrm{a}(\nabla \times \overrightarrow{\mathrm{b}})+(\vec{\nabla} \mathrm{a}) \times \overrightarrow{\mathrm{b}}$ :
$=\frac{l}{c}\left[\int_{\text {wire }} \frac{1}{r}(\vec{\nabla} \times d \vec{l})+\vec{\nabla} \frac{1}{r} \times d \vec{l}\right]=\frac{l}{c} \int_{\text {wire }} \frac{1}{r}(\vec{\nabla} \times d \vec{l})+\vec{\nabla} \frac{1}{r} \times d \vec{l}$
Since $\vec{\nabla} \times d \vec{l}=0$ and $\vec{\nabla} \frac{1}{r}=-\frac{\hat{r}}{r^{2}}$ :

$$
\Rightarrow \quad \overrightarrow{\mathrm{B}}=\frac{l}{c} \int_{\text {wire }} d \vec{l} \times \frac{\hat{r}}{r^{2}}
$$

## Biot-Savart Law: illustration

- Biot-Savart: $\mathrm{d} \overrightarrow{\mathrm{B}}=\frac{l}{c} d \vec{l} \times \frac{\hat{r}}{r^{2}}$

- dB is perpendicular to current and to radial direction
- E.g.: if you have dl // x, r// y $\rightarrow \mathrm{B} / / \mathrm{z}$


## Application of Biot-Savart:



- Calculate B created by a loop of current
- Radius: R
- Distance from center of the loop: z
- Solution on axis
- Apply Biot-Savart
- Determine direction of dB
- Symmetry $\rightarrow$ only component // z survives
$\mathrm{B}=\int_{\text {wire }}(\mathrm{d} \overrightarrow{\mathrm{B}})_{z}=\int_{\text {wire }} \frac{l}{c r^{2}}|d \vec{l} \times \hat{r}| \sin \theta$
 $|d \vec{l} \times \hat{r}|=|d \vec{l}|=R d \varphi ; \quad \sin \theta=R / r ; r=\sqrt{R^{2}+h^{2}}$

$$
\vec{B}=\frac{l}{c r^{2}} R \sin \theta \int_{0}^{2 \pi} d \varphi \hat{z}=\frac{2 \pi / R^{2}}{C\left(R^{2}+z^{2}\right)^{3 / 2}} \hat{z} \Rightarrow \vec{B}_{100 p \text { center }}=\frac{2 \pi /}{C R} \hat{z}
$$

## Application of Biot-Savart:

## B from solenoid

- What if we stack a N rings over a length L ?
- Use result of single loop + superposition:

Single ring: $d \vec{B}=\frac{2 \pi R^{2}}{c\left(\mathrm{R}^{2}+\mathrm{Z}^{2}\right)^{3 / 2}} d l$
Integrate on all rings (in the middle of the solenoid)
$\vec{B}=\int_{-L / 2}^{L / 2} \frac{2 \pi R^{2}}{c\left(R^{2}+z^{2}\right)^{3 / 2}} n / d z=\frac{2 \pi n /}{c} \int_{-L / 2}^{L / 2} \frac{R^{2} d z}{\left(R^{2}+z^{2}\right)^{3 / 2}}$
$=\frac{2 \pi n I}{c} \frac{2 L}{\sqrt{L^{2}+4 R^{2}}}$
With $n=N / L$

- For $\mathrm{L} \gg \mathrm{R}: \quad \vec{B}=\frac{4 \pi n l}{C}$



## Solenoid and Ampere's law

- One can prove that B outside the solenoid is $=0$
- Ampere can be used to simply prove that B does not depend on r:

$\oint_{\text {retange }} \vec{e} \cdot d \vec{l}=\frac{4 \pi}{c} /_{\text {end }}$
Since $\vec{B}$ is //z and present only inside the solenoid:
$B(r) L=\frac{4 \pi}{C} N I \Rightarrow B(r)=\frac{4 \pi}{C} \frac{N}{L} I=\frac{4 \pi}{C} n /$ no dependence on R
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## Solenoid's magnetic field: demos

- Expected:

- Can we test this experimentally?
- G12: B from a single wire using iron filings
- G13: B from 2 wires
- G16: B inside solenoid


## More demos on magnetic fields

- More demos:
- G14: map B around a wire using a compass
- G9a: collapsing solenoid
- Can you explain what's happening?
- G18: Long solenoid
- Long solenoid with $N_{\text {turn }}=2760, I=4.5 \mathrm{~mA}$, length $=46 \mathrm{~cm}$ - ( $\mathrm{R}=10 \Omega, \mathrm{~L}=128 \mathrm{mH}$ )
- What is B ?

$$
B=\frac{4 \pi}{c} n I=\frac{4 \pi}{3 \cdot 10^{10}} \frac{2760}{50} 4.5=230 \cdot 10^{-8} \text { Gauss ??? }
$$

- Verify with Hall probe


## Thompson's experiment: variation

- Variation on a theme: instead of canceling effects of $E$ and $B$, one could tune the fields and measure the radius of curvature of the electron beam.
- Parameters of the problem:
- $\mathrm{V}=300 \mathrm{~V}$
- $\mathrm{I}=1.4 \mathrm{~A}$
- $R=5 \mathrm{~cm}$
- Solution:
- $\mathrm{e} / \mathrm{m}=2.02 \times 10^{11} \mathrm{C} / \mathrm{Kg}$ (cfr: $1.76 \times 10^{11} \mathrm{C} / \mathrm{Kg}$ )


## Summary and outlook

- Today:
- Toward Maxwell's equations: $\vec{\nabla} \cdot \vec{B}=0 \quad$ and $\quad \vec{\nabla} \times \vec{B}=\frac{4 \pi}{c} \vec{J}$
- Vector Potential: $\quad \vec{B} \equiv \vec{\nabla} \times \vec{A}$
- Biot-Savart Law: $\mathrm{d} \overrightarrow{\mathrm{B}}=\frac{l}{c} d \vec{l} \times \frac{\hat{r}}{r^{2}}$
- Next time:
- What happens when B varies in time?
- Faraday's and Lenz's laws and their applications

