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Introduction to Manufacturing Systems

# Single-part-type, multiple stage systems

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- Setup: A setup change occurs when it costs more to make a Type *j* part after making a Type *i* part than after making a Type *j* part.
- Examples:
  - \* Tool change (when making holes)
  - Die change (when making sheet metal parts)
  - \* Paint color change
  - Replacement of reels of components, when populating printed circuit cards

## Setups <sub>Costs</sub>

- Setup costs can include
  - $\star\,$  Money costs, especially in labor. Also materials.
  - $\star\,$  Time, in loss of capacity and delay.
- Some machines create scrap while being adjusted during a setup change.
- Setups motivate *lots* or *batches:* a set of parts that are processed without interruption by setups.

## Setups <sub>Costs</sub>

- Problem:
  - $\star\,$  Large lots lead to large inventories and long lead times.
  - $\star\,$  Small lots lead to frequent setup changes.

• Reduction of setup time has been a very important trend in modern manufacturing.

# Setups Flexibility

- *Flexibility:* a widely-used term whose meaning diminishes as you look at it more closely. (*This may be the definition of a <u>buzzword</u>.*)
- *Flexibility:* the ability to make many different things ie, to operate on many different parts.
- Agility is also sometimes used.

## Setups Flexibility

#### Which is more flexible?

- A machine that can hold 6 different cutting tools, and can change from one to another with zero setup time.
- A machine that can hold 25 different cutting tools, and requires a 30-second setup time.

#### Which is more flexible?

- A final assembly line that can produce all variations of 6 models of cars, and can produce 100 cars per day.
- A final assembly line that can produce all variations of 1 model at 800 cars per day?

#### Setup Machines vs Batch Machines

- A machine has setups when there are costs or delays associated with changing part types. Machines that require setups may make one or many parts at a time.
- A machine operates on batches of size n if it operates on up to n parts simultaneously each time it does an operation.
   Batch machines may or may not operate on different part types. If they do, they may or may not require setup changes. (Also, the batches may or may not be homogeneous.)
  - *Examples:* Ovens and chemical chamber operations in semiconductor manufacturing; chemical processing of liquids.

# Capacity

- Consider a machine that does operations on k part types. Assume the change-over time is 0 and that the machine is perfectly reliable.
- The time to do an operation on a type i part is  $\tau_i$ .
- We make  $U_i$  type i parts. If we have to make them in time T, we can do it if

$$\sum_{i=1}^{\kappa} U_i \tau_i \le T$$

• Define  $u_i = U_i/T$  to be the *production rate* of type *i* parts. Then we must have

$$\sum_{i=1}^{\kappa} \tau_i u_i \le 1$$

• This is the *capacity constraint* of the machine.

Setups Loss of Capacity

#### Assume

- there is one setup for every Q parts (Q=lot size),
- the setup time is S,
- the time to process a part is  $\tau$ .

Then the time to process Q parts is  $S + Q\tau$ . The average time to process one part is  $\tau + S/Q$ .

Setups Loss of Capacity

If the demand rate is d parts per time unit, then the demand is feasible only if

$$d < \frac{1}{\tau + S/Q} < \frac{1}{\tau}$$

This is not satisfied if S is too large or Q is too small.

Single-stage, multiple-part-type systems

- Focus on a single part type (simplification!)
- Short time scale (hours or days).
- Constant demand.
- Deterministic setup and operation times.
- Setup/production/(idleness) cycles.
- *Policy:* Produce at maximum rate until the inventory is enough to last through the next setup time.

### Cycle:

- S = setup period for the part type
- P = period the machine is operating on the part type
- I = period the machine is making or setting up for *other* parts, or idle



# **Production Objective**



Objective is to keep th cumulative production line close to the cumulative demand line.

Cycle:

- Setup period. Duration: S. Production: 0. Demand: Sd. Net change of surplus, ie of P - D is  $\Delta_S = -Sd$ .
- Production period. Duration:  $t = Q\tau$ . Production: Q. Demand: td. Net change of P - D is  $\Delta_P = Q - td = Q - Q\tau d = Q(1 - \tau d)$ .

- Idleness period (for the part we focus on).
   Duration: *I*. Production: 0. Demand: *Id*. Net change of *P* − *D* is Δ<sub>I</sub> = −*Id*.
- Total (desired) net change over a cycle: 0.
- Therefore, net change of P D over whole cycle is  $\Delta_S + \Delta_P + \Delta_I = -Sd + Q(1 - \tau d) - Id = 0.$

• Since  $I \ge 0$ ,  $Q(1 - \tau d) - Sd \ge 0$ .

• If 
$$I = 0$$
,  $Q(1 - \tau d) = Sd$ .

• If  $\tau d > 1$ , net change in P - D will be negative.

Single-stage, multiple-part-type systems

## Setups Production & inventory history



- Production period duration =  $Q\tau = 10$ .
- Idle period duration = 7.
- Total cycle duration = 20.
- Maximum inventory is  $Q(1 \tau d) = 5.$

# Setups Not frequent enough



- Production period duration =  $Q\tau = 30.$
- Idle period duration = 27.
- Total cycle duration = 60.
- Maximum inventory is  $Q(1 \tau d) = 15.$

# Setups Too frequent



• Batches too small – demand not met.

• 
$$Q(1 - \tau d) - Sd = -0.5$$

- Backlog grows.
- Too much capacity spent on setups.

# Setups Just right!



- Small batches small inventories.
- Maximum inventory is  $Q(1 - \tau d) = 1.5.$

Single-stage, multiple-part-type systems

## Setups Another set of parameters



## Setups Time in the system



- Each batch spends  $Q\tau + S$  time units in the system *if*  $Q(1 \tau d) Sd \ge 0.$
- Optimal batch size:  $Q = Sd/(1 - \tau d)$

### Setups Time in the system — Stochastic Example

• Batch sizes equal (Q); processing times random.

\* Average time to process a batch is  $Q\tau + S = 1/\mu$ .

• Random arrival times (exponential inter-arrival times)

\* Average time between arrivals of batches is  $Q/d = 1/\lambda$ .

• Infinite buffer for waiting batches

## Setups Time in the system — Stochastic Example



- Treat system as an M/M/1 queue in batches.
- Average delay for a batch is  $1/(\mu \lambda)$ .
- Variability increases delay .

## Setups Batch size data from a factory



## Setups Batch size data from a factory



Single-stage, multiple-part-type systems

## Setups Batch size data from a factory



Single-stage, multiple-part-type systems

- Assumptions:
  - \* Cycle is produce Type 1, setup for Type 2, produce Type 2, setup for Type 1.
  - $\star$  Unit production times:  $au_1, au_2$ .
  - \* Setup times:  $S_1, S_2$ .
  - \* Batch sizes:  $Q_1, Q_2$ .
  - \* Demand rates:  $d_1, d_2$ .
  - ⋆ No idleness.



Let T be the length of a cycle. Then

$$S_1 + \tau_1 Q_1 + S_2 + \tau_2 Q_2 = T$$

To satisfy demand,

$$Q_1 = d_1 T; \quad Q_2 = d_2 T$$

This implies

$$T = \frac{S_1 + S_2}{1 - (\tau_1 d_1 + \tau_2 d_2)}$$

Single-stage, multiple-part-type systems

- *τ<sub>i</sub>d<sub>i</sub>* is the fraction of time that is devoted to
   producing part *i*.
- $1 (\tau_1 d_1 + \tau_2 d_2)$  is the fraction of time that is *not* devoted to production.
- We must therefore have  $\tau_1 d_1 + \tau_2 d_2 < 1$ . This is a *feasibility condition*.

- New issue: Setup sequence .
  - \* In what order should we produce batches of different part types?
- $S_{ij}$  is the setup time (or setup cost) for changing from Type *i* production to Type *j* production.
- Problem:
  - $\label{eq:select} \star \ \, \mbox{Select the setup sequence } \{i_1,i_2,...,i_n\} \ \, \mbox{to minimize} \\ S_{i_1i_2}+S_{i_2i_3}+...+S_{i_{n-1}i_n}+S_{i_ni_1}. \ \ \, \mbox{}$

Cases

• Sequence-independent setups:  $S_{ij} = S_j$ . Sequence does not matter.

• Sequence-dependent setups: traveling salesman problem.

Cases

- Paint shop: *i* indicates paint color number.
- $S_{ij}$  is the time or cost of changing from Color i to Color j.
- If i > j, i is darker than j and  $S_{ij} > S_{ji}$ .



- Hierarchical setups.
- Operations have several attributes.
- Setup changes between some attributes can be done quickly and easily.
- Setup changes between others are lengthy and expensive.

- Wagner-Whitin (1958) problem
- Assumptions:
  - \* Discrete time periods (weeks, months, etc.); t = 1, 2, ..., T.
  - $\star\,$  Known, but non-constant demand  $D_1$ ,  $D_2$ , ...,  $D_T.$
  - $\star$  Production, setup, and holding cost.
  - ★ Infinite capacity.

- $c_t =$  production cost (dollars per unit) in period t
- $A_t =$ setup or order cost (dollars) in period t
- $h_t$  = holding cost; cost to hold one item in inventory from period t to period t + 1
- $I_t =$  inventory at the end of period t the state variable
- $Q_t =$ lot size in period t the decision variable

Problem formulation: minimize  $\sum_{t=1}^{T} (A_t \delta(Q_t) + c_t Q_t + h_t I_t)$ (where  $\delta(Q) = 1$  if Q > 0;  $\delta(Q) = 0$  if Q = 0)



#### Characteristic of Solution:



Single-stage, multiple-part-type systems

Characteristic of Solution:

• Either  $I_t = 0$  or  $Q_{t+1} = 0$ . That is, produce only when inventory is zero. Or,

\* If we assume  $I_j = 0$  and  $I_k = 0$  (k > j) and  $I_t > 0, t = j + 1, ..., k$ ,

 $\star \ \, \mbox{then} \ \, Q_j>0, \ \, Q_k>0, \ \, \mbox{and} \ \, Q_t=0, t=j+1,...,k.$ 

#### Then

•  $I_{j+1} = Q_j - D_j$ ,

• 
$$I_{j+2} = Q_j - D_j - D_{j+1}$$
, ...

• 
$$I_k = 0 = Q_j - D_j - D_{j+1} - \dots - D_k$$

Or,  $Q_j = D_j + D_{j+1} + ... + D_k$ 

which means produce enough to exactly satisfy demands for some number of periods, starting now.

This is not enough to determine the solution, but it means that the search for the optimal is limited.

## Setups Real-Time Scheduling

• *Problem:* How to decide on batch sizes (ie, setup change times) in response to events.

Issue: Same as before.
 \* Changing too often causes capacity loss; changing too infrequently leads to excess inventory and lead time.

## Setups Real-Time Scheduling — One Machine, Two Part Types

Model:

- $d_i = \text{demand rate of Type } i$
- $\mu_i = 1/\tau_i = \text{maximum production rate of Type } i$
- S =setup time
- $u_i(t) =$ production rate of Type i at time t
- $x_i(t) =$ surplus (inventory or backlog) of Type i

• 
$$\frac{dx_i}{dt} = u_i(t) - d_i, i = 1, 2$$



- Draw two lines, labeled *Setup 1* and *Setup 2*.
- Keep the system in setup *i* until x(t) hits the *Setup j* line.
- Change to setup *j*.
- Etc.











## Setups Real-Time Scheduling — Corridor Policy Heuristic

• In this version, batch size is a function of time.

• Also possible to pick parallel boundaries, with an upper limit. Then batch size is constant until upper limit reached.

## Setups Real-Time Scheduling — Corridor Policy Heuristic

Two possibilities (for two part types):

- Converges to limit cycle only if demand is within capacity, ie if  $\sum_i \tau_i d_i < 1$ .
- Diverges if
  - $\star$  demand is not within capacity, or
  - \* corridor boundaries are poorly chosen.

## Setups Real-Time Scheduling — Corridor Policy Heuristic

Three possibilities for more than two part types:

- Limit cycle only if demand is within capacity,
- Divergence if
  - $\star$  demand is not within capacity, or
  - $\star$  corridor boundaries are poorly chosen.
- *Chaos* if demand is within capacity, and corridor boundaries chosen ... not well?

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