# 2.25 - Fluid Mechanics <br> Overview of Lagrangian and Eulerian Descriptions 

## Lagrangian Description

In the Lagrangian perspective, we follow fluid particles (material points) as they move through the flow. Mathematically, we specify the vector field

$$
\begin{equation*}
\underline{X}\left(\underline{X}_{0}, t\right) \tag{1}
\end{equation*}
$$

where $\underline{X}$ is the position vector of a fluid particle at some time $t$ and $\underline{X}_{0}$ is the position vector of the particle at some reference time, say $t=t_{0}$. That is

$$
\begin{equation*}
\underline{X}_{0}=\underline{X}\left(\underline{X}_{0}, t=t_{0}\right) \tag{2}
\end{equation*}
$$

We defined the Lagrangian velocity as the time derivative of the position vector following a fluid particle:

$$
\begin{equation*}
\underline{V}=\left.\frac{d \underline{X}}{d t}\right|_{\substack{\text { single } \\ \text { particle }}} \tag{3}
\end{equation*}
$$

## Eulerian Description

On the other hand, the Eulerian perspective fixates on a particular point in space, and records the properties of the fluid elements passing through that point. Mathematically, specify

$$
\begin{equation*}
\underline{v}(\underline{x}, t) \tag{4}
\end{equation*}
$$

where $\underline{v}$ is the velocity vector at the laboratory coordinate $\underline{x}$ at time $t$.
One way to connect the Lagrangian and Eulerian descriptions is

$$
\begin{equation*}
\underline{v}\left(\underline{x}=\underset{\text { Eulerian }}{X}\left(\underline{X}_{0}, t\right), t\right)=\frac{d \underline{X}}{d t}\left(\underline{X}_{0}, t\right) . \tag{5}
\end{equation*}
$$

Both sides of equation (5) describe the velocity of the fluid particle that was at $\underline{X}_{0}$ at $t_{0}$, but is at the position $\underline{x}$ at time $t$.

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## Material Derivative

The material derivative gives us a way to relate the Lagrangian description to the Eulerian one. It is defined for a quantity $F$ (which could be a scalar or a vector) as

$$
\frac{D F}{D t}=\frac{\partial F}{\partial t}+(\underline{v} \cdot \underline{\nabla}) F
$$

In Cartesian coordinates, this is written as

$$
\frac{D F}{D t}=\left.\frac{\partial F}{\partial t}\right|_{\substack{x, y, z \\ \text { fixed }}}+\left.v_{x} \frac{\partial F}{\partial x}\right|_{\substack{t, y, z \\ \text { fixed }}}+\left.v_{y} \frac{\partial F}{\partial y}\right|_{\substack{t, x, z \\ \text { fixed }}}+\left.v_{z} \frac{\partial F}{\partial z}\right|_{\substack{t, x, y \\ \text { fixed }}}
$$

The material derivative can be used to obtain the ordinary differential equation describing the pathline of a particle. At any instant in time, the particle inhabits some laboratory point, described by $\underline{x}$. At some time $t$, the particle position $\underline{X}$ (in Lagrangian coordinates) is therefore equal to $\underline{x}$. Since the material derivative tells the Lagrangian time derivative in Eulerian coordinates, we can obtain the ODE we seek by setting

$$
\begin{equation*}
\left.\frac{d \underline{X}}{d t}\right|_{\substack{\text { single } \\ \text { particle }}} \equiv \frac{D \underline{\underline{x}}}{D t} \tag{6}
\end{equation*}
$$

The right-hand side can be thought of as the rate of change of the laboratory coordinate of the fluid particle of interest with time. Let us focus only on the $x$-coordinate of this particle. As shown in class, for this case the material derivative becomes

$$
\begin{equation*}
\left.\frac{d X}{d t}\right|_{\substack{\text { single } \\ \text { particle }}}=\frac{D x}{D t}=\left.\frac{\partial x}{\partial t}\right|_{\substack{x, y, z \\ \text { fixed }}}+\left.v_{x} \frac{\partial x}{\partial x}\right|_{\substack{t, y, z \\ \text { fixed }}}+\left.v_{y} \frac{\partial x}{\partial y}\right|_{\substack{t, x, z, z \\ \text { fixed }}}+\left.v_{z} \frac{\partial x}{\partial z}\right|_{\substack{t, x, y \\ \text { fixed }}}=0+v_{x}(1)+0+0=v_{x} . \tag{7}
\end{equation*}
$$

Similarly, the time evolution of the $y$-coordinate of the particle is described by

$$
\begin{equation*}
\left.\frac{d Y}{d t}\right|_{\substack{\text { single } \\ \text { particle }}}=\frac{D y}{D t}=\left.\frac{\partial y}{\partial t}\right|_{\substack{x, y, z \\ \text { fixed }}}+\left.v_{x} \frac{\partial y}{\partial x}\right|_{\substack{t, y, z \\ \text { fixed }}}+\left.v_{y} \frac{\partial y}{\partial y}\right|_{\substack{t, x, z \\ \text { fixed }}}+\left.v_{z} \frac{\partial y}{\partial z}\right|_{\substack{t, x, y \\ \text { fixed }}}=0+0+v_{y}(1)+0=v_{y} . \tag{8}
\end{equation*}
$$

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