

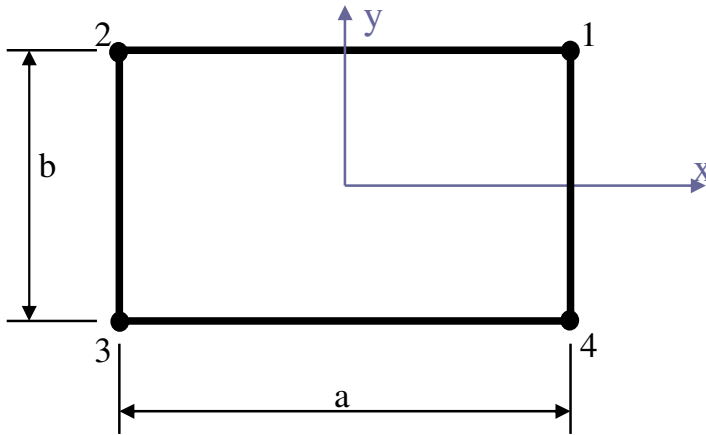
**2.092/2.093**  
**FINITE ELEMENT OF SOLIDS AND FLUIDS I**  
**FALL 2009**

**Homework 5- solution**

Instructor:	Prof. K. J. Bathe	Assigned:	Session10
TA:	Seounghyun Ham	Due:	Session12

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**Problem 1 (20 points):**



$$h_1 = \frac{1}{4} \left( 1 + \frac{2x}{a} \right) \left( 1 + \frac{2y}{b} \right)$$

$$h_2 = \frac{1}{4} \left( 1 - \frac{2x}{a} \right) \left( 1 + \frac{2y}{b} \right)$$

$$h_3 = \frac{1}{4} \left( 1 - \frac{2x}{a} \right) \left( 1 - \frac{2y}{b} \right)$$

$$h_4 = \frac{1}{4} \left( 1 + \frac{2x}{a} \right) \left( 1 - \frac{2y}{b} \right)$$

$$u = [h_1 \quad h_2 \quad h_3 \quad h_4] \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix}, v = [h_1 \quad h_2 \quad h_3 \quad h_4] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}$$

$$\varepsilon_{xx} = \frac{\partial u}{\partial x} = [h_{1,x} \quad 0 \quad h_{2,x} \quad 0 \quad h_{3,x} \quad 0 \quad h_{4,x} \quad 0] \underline{U}$$

$$\varepsilon_{yy} = \frac{\partial v}{\partial y} = \begin{bmatrix} 0 & h_{1,y} & 0 & h_{2,y} & 0 & h_{3,y} & 0 & h_{4,y} \end{bmatrix} \underline{U}$$

where  $\underline{U}^T = [u_1 \quad v_1 \quad u_2 \quad v_2 \quad u_3 \quad v_3 \quad u_4 \quad v_4]$ ;  $\varepsilon_{zz} = 0$

As  $\varepsilon_V = \varepsilon_{xx} + \varepsilon_{yy}$

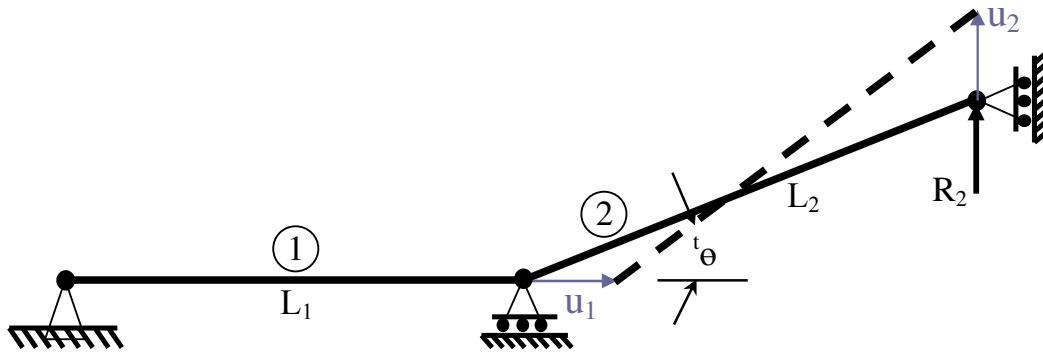
$$\therefore \varepsilon_V = \underline{B}_{\varepsilon V} \underline{U} = \begin{bmatrix} h_{1,x} & h_{1,y} & h_{2,x} & h_{2,y} & h_{3,x} & h_{3,y} & h_{4,x} & h_{4,y} \end{bmatrix} \underline{U}$$

Hence

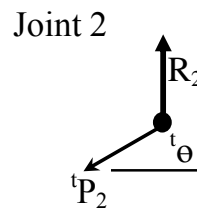
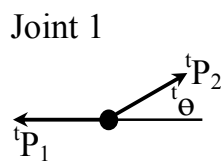
$$\underline{K} = t \int_{-\frac{b}{2}}^{\frac{b}{2}} \int_{-\frac{a}{2}}^{\frac{a}{2}} \beta \underline{B}_{\varepsilon V}^T \underline{B}_{\varepsilon V} dx dy$$


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**Problem 2 (20 points):**



Assuming tension in the bar as positive, the equilibrium of the joints gives:



$${}^tP_1 - {}^tP_2 \cos {}^t\theta = 0 \quad (1) \quad R_2 - {}^tP_2 \sin {}^t\theta = 0 \quad (2)$$

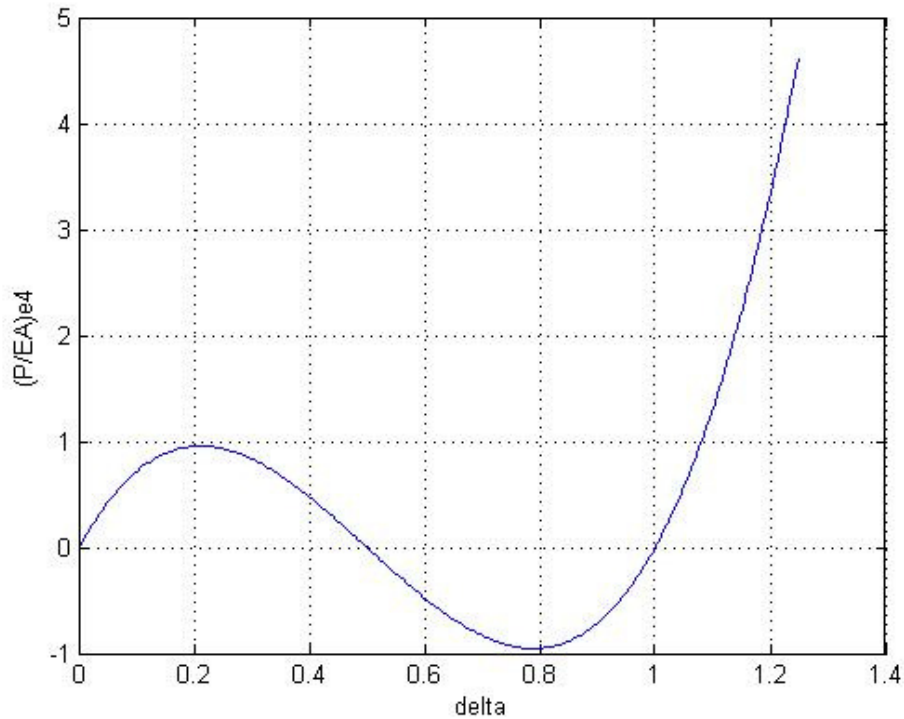
$${}^tP_1 = \frac{EA}{L_1} {}^t u_1, \quad {}^tP_2 = \frac{EA}{L_2} \delta L_2 \quad (3)$$

$$\text{where } \delta L_2 = \sqrt{(5 - {}^t u_1)^2 + (0.5 + {}^t u_2)^2} - L_2 \quad (4)$$

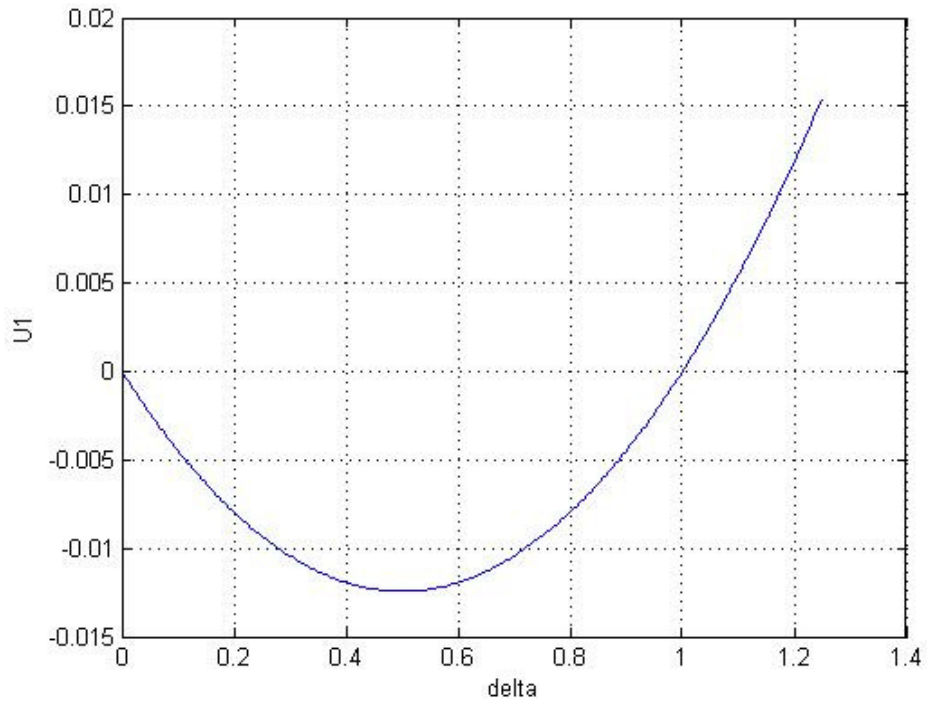
$$\text{From the geometry, } \tan {}^t\theta = \frac{0.5 + {}^t u_2}{5 - {}^t u_1}, \quad {}^t u_2 = -\Delta, \quad R_2 = -P \quad (5)$$

Eq. (1) and (2) are the force equilibrium equations. We use them by assuming a  $\Delta$ , solving from equation (1) for  ${}^t u_1$ , then substituting  ${}^t u_1$  and  $\Delta$  into the equation (2) to obtain the corresponding  $P$ . We can also solve them in different way. We first assume  ${}^t\theta$  and then calculate  ${}^t u_1$  and  $\Delta$ .

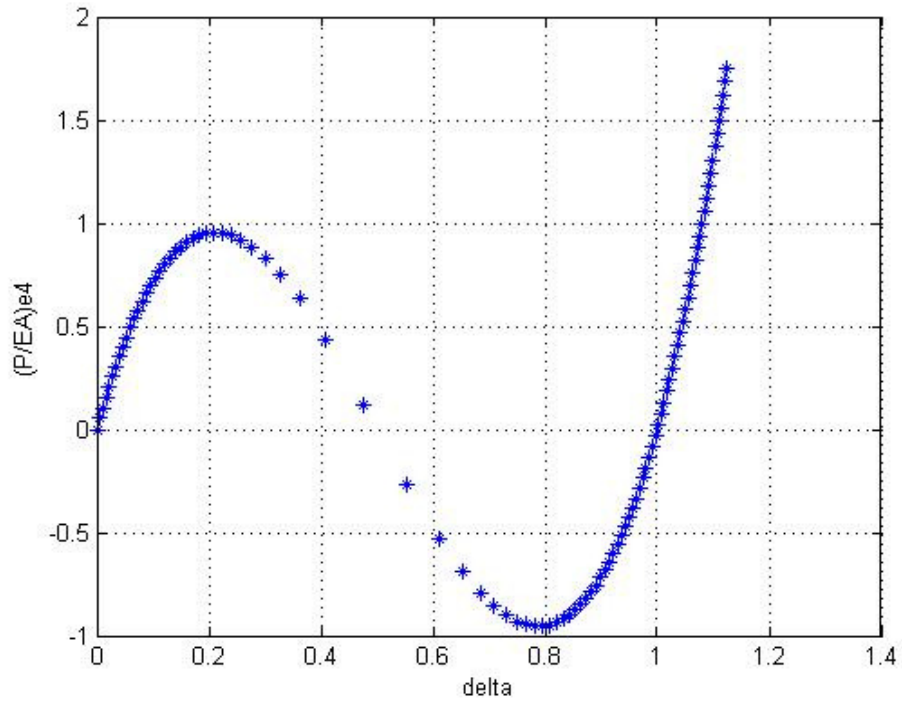
$$\frac{P}{EA} \times 10^4 \text{ Vs. } \Delta$$



Displacement  $u_1$  Vs.  $\Delta$



$\frac{P}{EA} \times 10^4$  Vs.  $\Delta$  Using ADINA



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2.092 / 2.093 Finite Element Analysis of Solids and Fluids I  
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