2.035: Midterm Exam - Part 1 (In class) Spring 2004

1.5 hours

You may use the notes you took in class but no other sources.

Please give reasons justifying each (nontrivial) step in your calculations.

<u>Problem 1</u>: Let R be a 3-dimensional Euclidean vector space and let $\{f_1, f_2, f_3\}$ be an arbitrary (not necessarily orthonormal) basis for R. Define a set of vectors $\{e_1, e_2, e_3\}$ by

$$egin{array}{rcl} m{e}_1 &=& m{f}_1, \ m{e}_2 &=& m{f}_2 + c_{21} m{e}_1, \ m{e}_3 &=& m{f}_3 + c_{31} m{e}_1 + c_{32} m{e}_2. \end{array}$$

- i) Calculate the values of the scalars c_{21}, c_{31} and c_{32} that makes $\{e_1, e_2, e_3\}$ a mutually orthogonal set of vectors.
- ii) Is the set $\{e_1, e_2, e_3\}$ linearly independent?
- iii) Does $\{e_1, e_2, e_3\}$ form an orthonormal basis for R?

<u>Problem 2</u>: Let R be the Euclidean vector space consisting of "trigonometric polynomials", a typical vector p having the form

$$\boldsymbol{p} = p(t) = \sum_{n=0}^{2} \alpha_n \cos nt$$
 where the $\alpha's$ span all real numbers.

The natural operations of addition and multiplication by a scalar are in force. The scalar product between two vectors p and q is taken to be

$$\boldsymbol{p} \cdot \boldsymbol{q} = \int_0^{2\pi} p(t)q(t) \, dt.$$

Let **A** be the tensor that carries a vector $\mathbf{p} = p(t)$ into its second derivative:

$$\boldsymbol{A}\boldsymbol{p}=p^{\prime\prime}(t).$$

- i) Is **A** singular or nonsingular?
- ii) Is **A** symmetric?
- iii) Determine the eigenvalues of A.

<u>Problem 3</u>: Let R be an arbitrary 3-dimensional vector space and let A be a linear transformation on R. (Note that R might not be Euclidean and A might not be symmetric.) Suppose that Ahas three real eigenvalues $\alpha_1, \alpha_2, \alpha_3$, and suppose that they are distinct: $\alpha_1 \neq \alpha_2 \neq \alpha_3 \neq \alpha_1$. Let a_1, a_2, a_3 be the corresponding eigenvectors.

- i) Show that any pair of these eigenvectors, e.g. $\{a_1, a_2\}$, is a linearly independent pair of vectors.
- ii) Next show that $\{a_1, a_2, a_3\}$ is a linearly independent set of vectors.