2.032 DYNAMICS

Problem Set No. 2

Out: Wednesday, September 22, 2004

Due: Wednesday, September 29, 2004 at the beginning of class

Problem 1

Show that for any 3×3 skew-symmetric matrix *A*, there exists a 3-dimensional vector ω such that for any three-dimensional vector *x*,

$$Ax = \omega \times x$$
.

Problem 2

Consider the coupled pendula shown in the figure below. Both rods are massless, with point masses *m* attached to their ends. Both joints shown in the figure are frictionless. The external force *F* encloses a fixed angle γ with the line of the pendulum shown. The masses never collide. The constant of gravity is *g*.

Questions:

- Identify the constraints.
- Determine the number of degrees of freedom.
- Find the equations of motion for ϕ and ψ .
- Find the constraint forces.
- Is the system conservative? (Why?)



Problem 3

Determine the angular velocity of a cone rolling on the *XY* -plane without slipping, as shown.



Figure by OCW.

Problem 4 (adapted from Ginsberg, 3-22)

The disk rotates at ω_1 about its axis, and the rotation rate of the forked shaft is ω_2 . Both rates are constant. Determine the velocity and acceleration of an arbitrarily selected point B on the perimeter. Describe the results in terms of components relative to the *xyz* axes in the sketch.



Figure by OCW. After 3-22 in Ginsberg, J. H. Advanced Engineering Dynamics. 2nd ed. New York: Cambridge University Press, 1998.