## Lecture 12.

## **13** Stratified Spaces

**Definition 13.1.** A stratification of a topological space X is a filtraion is a decomposition  $X = \bigcup_{i=0}^{n} S_i$  where each of the  $S_i$  are smooth manifolds (possibily empty) of dimension *i* and so that

$$\overline{S_k} \setminus S_k \subset \bigcup_{i=0}^{k-1} S_i.$$

The closure  $\overline{S_k}$  is called the stratum of dimension *k*.

Note that any stratum of a strafied space is a stratified space in its own right.

Stratified spaces are useful because many results about smooth manifolds can be extended to stratified spaces. A good example is the space of matrices  $M_{k\times n}$ . The strata are the matrices of rank bounded above by a fixed number. (assume that  $k \leq n$ )

As an application of this result we will compute the low homotopy groups for the Stiefel manifolds,  $St_k(\mathbb{R}^n)$ . Recall that the Stiefel manifold is the space of k-frames in  $\mathbb{R}^n$ . Given a k-frame  $(v_1, v_2, \ldots, v_k)$  we get an injective linear map  $A : \mathbb{R}^k \to \mathbb{R}^n$  by sending the standard basis vectors  $e_i \to v_i$ . In other words we can identify the Stiefel manifold,  $V_k(\mathbb{R}^n)$ , with the open subset of hom $(\mathbb{R}^k, \mathbb{R}^n)$ consisting of injective maps. The compliment of  $V_k(\mathbb{R}^n)$  has a decomposition according to the dimension of the kernel of the map. To codify this set

$$R_l = \{A \in \hom(\mathbb{R}^k, \mathbb{R}^n) | \operatorname{Rank}(A)) = l\}.$$

We claim that in fact these  $R_l$  are submanifolds.

**Proposition 13.2.**  $R_l \subset \hom(\mathbb{R}^k, \mathbb{R}^n)$  is a smooth submanifold of codimension

$$(k-l)(n-l).$$

*Proof.* Fix  $A \in S_l$ . Write  $\mathbb{R}^k = \ker(A) \oplus \operatorname{Ran}(A^*)$  and  $\mathbb{R}^n = \ker(A^*) + \operatorname{Ran}(A)$ . Then with respect to this decomposition we can write

$$A = \begin{bmatrix} \bar{A} & 0\\ 0 & 0 \end{bmatrix}$$

and a nearby matrix as

$$B = A + \begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix}$$

**Lemma 13.3.** If  $\bar{A} + \alpha$  is invertible then a vector (v, w) is in the kernel of *B* if and only if  $v = -(\bar{A} + \alpha)^{-1}\beta w$  and  $(\delta - \gamma (\bar{A} + \alpha)^{-1}\beta)v = 0$ 

*Proof.* If (v, w) is the the kernel of B then

$$(A+\alpha)v + \beta w = 0$$

so the first equation is clear. The second equation follows by substituting the first into

$$\gamma v + \delta w = 0$$

The lemma implies that the kernel of B is l-dimensional if and only if

$$\delta - \gamma (\bar{A} + \alpha)^{-1} \beta = 0$$

The map

$$\begin{bmatrix} \alpha & \beta \\ \gamma & \delta \end{bmatrix} \mapsto \delta - \gamma (\bar{A} + \alpha)^{-1} \beta$$

is clearly a submersion so the preimage of 0, our local model of  $R_l$  is a submanifold of codimension

$$\dim(\ker(A))\dim(\operatorname{Coker}(A)) = (k-l)(n-l).$$

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We'll use this to do a simple calculation of homotopy groups.

$$\pi_i(\operatorname{St}_k(\mathbb{R}^n) = 0)$$

for i < n - k. From its definition  $St_k(\mathbb{R}^n)$  can be identified with the space of matrices of maximal rank in  $M_{k \times n}$  and so

$$\operatorname{St}_k(\mathbb{R}^n) = M_{k \times n} \setminus (\bigcup_{l=0}^{k-1} R_l)$$

so the problem is to show that a map

$$f: S^i \to \operatorname{St}_k(\mathbb{R}^n)$$

from a sphere of dimension i < n - k is null homotopic. We know that there is a null-homotopy in the larger contractible space of matrices that is to say there is a map

$$h: D^{i+1} \to M_{k \times n}.$$

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so that

$$h|_S^i = f.$$

If we can find a homotopy  $k : I \times D^{i+1} \to M_{k \times n}$  so that during the homotopy the following two conditions hold.

- 1.  $k|I \times S^i \subset \operatorname{St}_k(\mathbb{R}^n)$
- 2.  $k(\{1\} \times D^{i+1}) \subset \operatorname{St}_k(\mathbb{R}^n)$ .

To see that we can do this we will appeal to Sard's theorem. Lets consider the larger family of maps

$$H: M_{k \times n} \times D^{i+1} \to M_{k \times n}$$

given by

$$H(A, x) = A + h(x).$$

If *A* is small enough then

$$k(t, x) = H(tA, x) = tA + f(x)$$

satisfies the first condition. To see that we can arrange that the second condition is satisfied we note that H is a submersion. Thus the preimages of the  $R_l$ 's are all submanifolds. Set

$$\tilde{R}_l = H^{-1}(R_l)$$

these are submanifolds of codimension (k - l)(n - l). so they have dimension

$$i + 1 + nk - (k - l)(n - l)$$

Consider the projection  $\tilde{R}_l \to M_{k \times n}$ . Provided that for all  $l \le k - 1$ 

$$i + 1 + nk - (k - l)(n - l) < nk$$

then image of the projection has measure zero. The worst case is l = k - 1 when the right hand side is

$$i + nk + k - n$$

so that the inequality holds if i < n - k. If  $(A, x) \ni \tilde{R}_l$  that for all  $x f(x) \ni R_l$  completing the proof.