18.726 Algebraic Geometry Spring 2009

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18.726: Algebraic Geometry (K.S. Kedlaya, MIT, Spring 2009) Divisors, linear systems, and projective embeddings (updated 1 Apr 09)

We conclude the first half of the course by translating into the language of schemes some classical notions related to the concept of a *divisor*. This will serve to explain (in part) why we will be interested in the cohomology of quasicoherent sheaves.

In order to facilitate giving examples, I will mostly restrict to *locally noetherian* schemes. See Hartshorne II.6 for divisors, and IV.1 for Riemann-Roch.

1 Weil divisors

Introduce Hartshorne's hypothesis (*): let X be a scheme which is noetherian, integral, separated, and regular in codimension 1. The latter means that for each point $x \in X$ whose local ring $\mathcal{O}_{X,x}$ has Krull dimension 1, that local ring must be regular.

Lemma. Let A be a noetherian local ring of dimension 1. Then the following are equivalent.

- (a) A is regular.
- (b) A is normal.
- (c) A is a discrete valuation ring.

(This is why normalizing a one-dimensional noetherian ring produces a regular ring.)

Warning: for a noetherian integral domain, normal implies regular in codimension 1 but not conversely. You have to add Serre's condition S2: for $a \in A$, every associated prime of the principal ideal (a) has codimension 1 when a is not a zerodivisor, and has codimension 0 when a = 0.

A prime (Weil) divisor on X is a closed integral (irreducible and reduced) subscheme of codimension 1. A formal \mathbb{Z} -linear combination of prime divisors is called a Weil divisor. If only nonnegative coefficients are used, we say the divisor is effective.

For example, let K(X) be the function field of X, i.e., the local ring of X at its generic point. (This equals $\operatorname{Frac}(\mathcal{O}(U))$ for any nonempty open affine subscheme U of X.) For $f \in K(X)$ nonzero, we can define a principal divisor associated to f as follows. For each prime divisor Z on X, let η_Z be the generic point of Z. Then \mathcal{O}_{X,η_Z} is a discrete valuation ring; let v_Z be the valuation. Now define the divisor

$$(f) = \sum_{Z} v_{Z}(f)Z;$$

this makes sense because only finitely many $v_Z(f)$ are nonzero. (That's because f restricts to an invertible regular function on some nonempty open subscheme U of X, and $v_Z(f) = 0$ whenever $Z \nsubseteq X - U$.)

Let Div X be the group of Weil divisors of X. The principal divisors form a subgroup (since (f) + (g) = (fg)); the quotient by this subgroup is called the *divisor class group* of

X, denoted $\operatorname{Cl} X$. For example, if $X = \operatorname{Spec}(A)$ with A a Dedekind domain, then $\operatorname{Div} X$ is the group of fractional ideals, and $\operatorname{Cl} X$ is the ideal class group. We say two divisors which differ by a principal divisor are *linearly equivalent*.

There are a number of examples in Hartshorne. One of my favorites is that of an *elliptic curve*; here is a summary. Let k be an algebraically closed field (for starters). Let $P(x,y,z) \in k[x,y,z]$ be a homogeneous polynomial of degree 3 defining a nonsingular subvariety C of \mathbb{P}^2_k . Pick a point $O \in C(k)$. There is a surjective map Div $X \to \mathbb{Z}$ mapping each prime divisor P to 1, called the *degree*. This map factors through Cl(X) because each principal divisor has degree 0. The kernel of the degree map $Cl(X) \to \mathbb{Z}$ is generated by $P(X) \to P(k)$. In fact it is equal to the set of such elements: given $P(X) \to P(X)$ we first draw the line through $P(X) \to P(X)$ and find its third intersection point $P(X) \to P(X)$ with $P(X) \to P(X)$ and $P(X) \to P(X)$ and find its third intersection point $P(X) \to P(X)$ with $P(X) \to P(X)$ and $P(X) \to P(X)$ and find its third intersection point $P(X) \to P(X)$. Then

$$(P) + (Q) + (R) \sim (R) + (S) + (O),$$

SO

$$(P) - (O) + (Q) - (O) \sim (S) - (O).$$

2 Cartier divisors

When the scheme X is not regular, there is a more restrictive notion of divisors that turns out to be more useful in many cases.

Let K be the locally constant sheaf associated to the function field K(X). A Cartier divisor on X is a section of the sheaf $K(X)/\mathcal{O}^{\times}$. Using the construction of principal divisors, we obtain a map from Cartier divisors to Weil divisors: if the Cartier divisor is represented on some open subset U of X by the rational function $f \in K(X)$, then the Weil divisor we get should agree with (f) when restricted to U (i.e., only keep the components of those prime divisors meeting U). This map is injective if X is normal, because an integrally closed noetherian domain is the intersections of its localizations at minimal prime ideals.

Proposition (Hartshorne, Proposition II.6.11). Suppose X is locally factorial (i.e., each local ring $\mathcal{O}_{X,x}$ is a unique factorization domain). Then the previous map is an isomorphism. (In particular, this holds if X is regular, because a regular local ring is factorial by a not-so-easy theorem of commutative algebra.)

Example: if $X = \operatorname{Spec} k[x, y, z]/(xy - z^2)$, the ideal (x, z) defines a Weil divisor which is not a Cartier divisor.

Again, there is an obvious notion of a *principal Cartier divisor*, namely one defined by a single element of K(X). The group of Cartier divisors modulo principal divisors is called the *Cartier class group* of X, denoted $\operatorname{CaCl} X$.

3 The Picard group

The Cartier class group is "usually" the same as the *Picard group*, namely the group of invertible sheaves on X under the tensor product. Namely, if D is a Cartier divisor on X, let $\mathcal{L}(D)$ be the subsheaf of \mathcal{K} such that

$$\mathcal{L}(D)(U) = \{ f \in K(X) : ((f) + (D))|_{U} \ge 0 \}.$$

Assuming that X is normal, this is locally free of rank 1, hence an invertible sheaf. This gives a homomorphism from Cartier divisors to the Picard group, which we see kills the principal divisors. The resulting homomorphism is always injective, even without any hypotheses on X (Hartshorne, Corollary II.6.14) but may not be surjective; however, it is surjective if X is integral (Hartshorne, Proposition II.6.15).

Note that if D is effective, then the function 1 defines a global section of $\mathcal{L}(D)$. Since \mathcal{L} is locally principal, we can locally identify \mathcal{L} with \mathcal{O}_X ; when we do so, the subsheaf of $\mathcal{L}(D)$ generated by 1 goes into correspondence with an ideal sheaf of \mathcal{O}_X , which doesn't depend on any choices. This ideal sheaf defines D as a closed subscheme. In other words, D is the zero locus of a certain section of $\mathcal{L}(D)$. More generally, even if D is effective, we can view D as the zero locus of a meromorphic section of $\mathcal{L}(D)$ (meaning a zero locus of $\mathcal{L}(D) \otimes_{\mathcal{O}_X} \mathcal{K}_X$), and indeed the zero locus of any meromorphic section of $\mathcal{L}(D)$ is linearly equivalent to D.

4 Linear systems

Suppose X is an integral separated scheme of finite type over a field k (which need not be algebraically closed). Let \mathcal{L} be an invertible sheaf on X. A linear system defined by \mathcal{L} is the set of zero loci of some k-linear subspace H of $H^0(X, \mathcal{L})$. If we take the entire space, that is called the *complete linear system* defined by \mathcal{L} .

We can attempt to use the elements of H to define a map $X \to \mathbb{P}^n_k$, where $n = \dim_k(H) - 1$. This might fail to give a morphism because H may have a base point, i.e., a point in the intersection of all of the divisors in the linear system. In fact, we get a morphism $X \to \mathbb{P}^n_k$ if and only if H has no base points.

Suppose now that k is algebraically closed, and that X is one-dimensional, projective, irreducible, and nonsingular (i.e., a "curve"). Consider the complete linear system associated to $\mathcal{L}(D)$ for some divisor D.

- (a) We get a map $X \to \mathbb{P}^n_k$ if and only if for each closed point $x \in X$, we have $\dim_k H^0(X, \mathcal{L}(D-x)) = \dim_k H^0(X, \mathcal{L}(D)) 1$. (In other words, there must be a section of $\mathcal{L}(D)$ not vanishing at x.)
- (b) The map in (a) is injective as a map of sets if and only if for each pair of distinct closed points $x, y \in X$, we have $\dim_k H^0(X, \mathcal{L}(D-x-y)) = \dim_k H^0(X, \mathcal{L}(D)) 2$. (In other words, there must be a section of $\mathcal{L}(D)$ vanishing at x but not at y, and vice versa.)

(c) The map in (b) is a closed immersion if and only if for each closed point $x \in X$, we have dim $H^0(X, \mathcal{L}(D-2x)) = \dim_k H^0(X, \mathcal{L}(D)) - 2$. (In other words, there must be a section of $\mathcal{L}(D)$ not vanishing at x, and a section vanishing to exact order 1 at x.)

(Condition (c) is needed to ensure that the tangent space at x embeds into the tangent space at the image of x. See Remark 7.8.2.)

Since we would like to know under what circumstances X embeds into a projective space, we would like to be able to compute at least the dimension of $H^0(X, \mathcal{L}(D))$ for each divisor D. This quest is greatly abetted by the Riemann-Roch theorem, more on which next time.