# 18.175: Lecture 31 

More Markov chains

Scott Sheffield<br>MIT

## Outline

Recollections

General setup and basic properties

Recurrence and transience

## Outline

## Recollections

## General setup and basic properties

## Recurrence and transience

## Markov chains

- Consider a sequence of random variables $X_{0}, X_{1}, X_{2}, \ldots$ each taking values in the same state space, which for now we take to be a finite set that we label by $\{0,1, \ldots, M\}$.
- Interpret $X_{n}$ as state of the system at time $n$.
- Sequence is called a Markov chain if we have a fixed collection of numbers $P_{i j}$ (one for each pair $i, j \in\{0,1, \ldots, M\}$ ) such that whenever the system is in state $i$, there is probability $P_{i j}$ that system will next be in state $j$.
- Precisely, $P\left\{X_{n+1}=j \mid X_{n}=i, X_{n-1}=i_{n-1}, \ldots, X_{1}=i_{1}, X_{0}=i_{0}\right\}=P_{i j}$.
- Kind of an "almost memoryless" property. Probability distribution for next state depends only on the current state (and not on the rest of the state history).


## Matrix representation

- To describe a Markov chain, we need to define $P_{i j}$ for any $i, j \in\{0,1, \ldots, M\}$.
- It is convenient to represent the collection of transition probabilities $P_{i j}$ as a matrix:

$$
A=\left(\begin{array}{cccc}
P_{00} & P_{01} & \ldots & P_{0 M} \\
P_{10} & P_{11} & \ldots & P_{1 M} \\
\cdot & & & \\
\cdot & & & \\
\cdot & & & \\
P_{M 0} & P_{M 1} & \ldots & P_{M M}
\end{array}\right)
$$

- For this to make sense, we require $P_{i j} \geq 0$ for all $i, j$ and $\sum_{j=0}^{M} P_{i j}=1$ for each $i$. That is, the rows sum to one.


## Powers of transition matrix

- We write $P_{i j}^{(n)}$ for the probability to go from state $i$ to state $j$ over $n$ steps.
- From the matrix point of view

$$
\left(\begin{array}{cccc}
P_{00}^{(n)} & P_{01}^{(n)} & \ldots & P_{0 M}^{(n)} \\
P_{10}^{(n)} & P_{11}^{(n)} & \ldots & P_{1 M}^{(n)} \\
\cdot & & & \\
\cdot & & & \\
\cdot & & & \\
P_{M 0}^{(n)} & P_{M 1}^{(n)} & \ldots & P_{M M}^{(n)}
\end{array}\right)=\left(\begin{array}{cccc}
P_{00} & P_{01} & \ldots & P_{0 M} \\
P_{10} & P_{11} & \ldots & P_{1 M} \\
\cdot & & & \\
\cdot & & & \\
\cdot & & & \\
P_{M 0} & P_{M 1} & \ldots & P_{M M}
\end{array}\right)^{n}
$$

- If $A$ is the one-step transition matrix, then $A^{n}$ is the $n$-step transition matrix.


## Ergodic Markov chains

- Say Markov chain is ergodic if some power of the transition matrix has all non-zero entries.
- Turns out that if chain has this property, then $\pi_{j}:=\lim _{n \rightarrow \infty} P_{i j}^{(n)}$ exists and the $\pi_{j}$ are the unique non-negative solutions of $\pi_{j}=\sum_{k=0}^{M} \pi_{k} P_{k j}$ that sum to one.
- This means that the row vector

$$
\pi=\left(\begin{array}{llll}
\pi_{0} & \pi_{1} & \ldots & \pi_{M}
\end{array}\right)
$$

is a left eigenvector of $A$ with eigenvalue 1, i.e., $\pi A=\pi$.

- We call $\pi$ the stationary distribution of the Markov chain.
- One can solve the system of linear equations $\pi_{j}=\sum_{k=0}^{M} \pi_{k} P_{k j}$ to compute the values $\pi_{j}$. Equivalent to considering $A$ fixed and solving $\pi A=\pi$. Or solving $(A-I) \pi=0$. This determines $\pi$ up to a multiplicative constant, and fact that $\sum \pi_{j}=1$ determines the constant.


## Examples

- Random walks on $\mathbb{R}^{d}$.
- Branching processes: $p(i, j)=P\left(\sum_{m=1}^{i} \xi_{m}=j\right)$ where $\xi_{i}$ are i.i.d. non-negative integer-valued random variables.
- Renewal chain (deterministic unit decreases, random jump when zero hit).
- Card shuffling.
- Ehrenfest chain ( $n$ balls in two chambers, randomly pick ball to swap).
- Birth and death chains (changes by $\pm 1$ ). Stationarity distribution?
- M/G/1 queues.
- Random walk on a graph. Stationary distribution?
- Random walk on directed graph (e.g., single directed chain).
- Snakes and ladders.


## Outline

Recollections

General setup and basic properties

Recurrence and transience

## Outline

## Recollections

General setup and basic properties

## Recurrence and transience

## Markov chains: general definition

- Consider a measurable space $(S, \mathcal{S})$.
- A function $p: S \times \mathcal{S} \rightarrow \mathbb{R}$ is a transition probability if
- For each $x \in S, A \rightarrow p(x, A)$ is a probability measure on $S, \mathcal{S})$.
- For each $A \in S$, the map $x \rightarrow p(x, A)$ is a measurable function.
- Say that $X_{n}$ is a Markov chain w.r.t. $\mathcal{F}_{n}$ with transition probability $p$ if $P\left(X_{n+1} \in B \mid \mathcal{F}_{n}\right)=p\left(X_{n}, B\right)$.
- How do we construct an infinite Markov chain? Choose $p$ and initial distribution $\mu$ on $(S, \mathcal{S})$. For each $n<\infty$ write

$$
\begin{gathered}
P\left(X_{j} \in B_{j}, 0 \leq j \leq n\right)=\int_{B_{0}} \mu\left(d x_{0}\right) \int_{B_{1}} p\left(x_{0}, d x_{1}\right) \cdots \\
\int_{B_{n}} p\left(x_{n-1}, d x_{n}\right) .
\end{gathered}
$$

Extend to $n=\infty$ by Kolmogorov's extension theorem.

## Markov chains

- Definition, again: Say $X_{n}$ is a Markov chain w.r.t. $\mathcal{F}_{n}$ with transition probability $p$ if $P\left(X_{n+1} \in B \mid \mathcal{F}_{n}\right)=p\left(X_{n}, B\right)$.
- Construction, again: Fix initial distribution $\mu$ on $(S, \mathcal{S})$. For each $n<\infty$ write

$$
\begin{gathered}
P\left(X_{j} \in B_{j}, 0 \leq j \leq n\right)=\int_{B_{0}} \mu\left(d x_{0}\right) \int_{B_{1}} p\left(x_{0}, d x_{1}\right) \cdots \\
\int_{B_{n}} p\left(x_{n-1}, d x_{n}\right) .
\end{gathered}
$$

Extend to $n=\infty$ by Kolmogorov's extension theorem.

- Notation: Extension produces probability measure $P_{\mu}$ on sequence space $\left(S^{0,1, \ldots}, \mathcal{S}^{0,1, \ldots}\right)$.
- Theorem: $\left(X_{0}, X_{1}, \ldots\right)$ chosen from $P_{\mu}$ is Markov chain.
- Theorem: If $X_{n}$ is any Markov chain with initial distribution $\mu$ and transition $p$, then finite dim. probabilities are as above.


## Markov properties

- Markov property: Take $\left(\Omega_{0}, \mathcal{F}\right)=\left(S^{\{0,1, \ldots\}}, \mathcal{S}^{\{0,1, \ldots\}}\right)$, and let $P_{\mu}$ be Markov chain measure and $\theta_{n}$ the shift operator on $\Omega_{0}$ (shifts sequence $n$ units to left, discarding elements shifted off the edge). If $Y: \Omega_{0} \rightarrow \mathbb{R}$ is bounded and measurable then

$$
E_{\mu}\left(Y \circ \theta_{n} \mid \mathcal{F}_{n}\right)=E_{X_{n}} Y
$$

- Strong Markov property: Can replace $n$ with a.s. finite stopping time $N$ and function $Y$ can vary with time. Suppose that for each $n, Y_{n}: \Omega_{n} \rightarrow \mathbb{R}$ is measurable and $\left|Y_{n}\right| \leq M$ for all $n$. Then

$$
E_{\mu}\left(Y_{N} \circ \theta_{N} \mid \mathcal{F}_{N}\right)=E_{X_{N}} Y_{N},
$$

where RHS means $E_{X} Y_{n}$ evaluated at $x=X_{n}, n=N$.

## Properties

- Property of infinite opportunities: Suppose $X_{n}$ is Markov chain and

$$
P\left(\cup_{m=n+1}^{\infty}\left\{X_{m} \in B_{m}\right\} \mid X_{n}\right) \geq \delta>0
$$

on $\left\{X_{n} \in A_{n}\right\}$. Then $P\left(\left\{X_{n} \in A_{n}\right.\right.$ i.o. $\}-\left\{X_{n} \in B_{n}\right.$ i.o. $\left.\}\right)=0$.

- Reflection principle: Symmetric random walks on $\mathbb{R}$. Have $P\left(\sup _{m \geq n} S_{m}>a\right) \leq 2 P\left(S_{n}>a\right)$.
- Proof idea: Reflection picture.


## Outline

Recollections

General setup and basic properties

Recurrence and transience

## Outline

## Recollections <br> General setup and basic properties

Recurrence and transience

## Query

- Interesting question: If $A$ is an infinite probability transition matrix on a countable state space, what does the (infinite) matrix $I+A+A^{2}+A^{3}+\ldots=(I-A)^{-1}$ represent (if the sum converges)?
- Question: Does it describe the expected number of $y$ hits when starting at $x$ ? Is there a similar interpretation for other power series?
- How about $e^{A}$ or $e^{\lambda A}$ ?
- Related to distribution after a Poisson random number of steps?


## Recurrence

- Consider probability walk from $y$ ever returns to $y$.
- If it's 1 , return to $y$ infinitely often, else don't. Call y a recurrent state if we return to $y$ infinitely often.

MIT OpenCourseWare
http://ocw.mit.edu

### 18.175 Theory of Probability

Spring 2014

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.

