18.085 Computational Science and Engineering I Fall 2008

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## Your PRINTED name is: <u>SOLUTIONS</u> Grading 1 2 3

1) (36 pts.) (a) Suppose u(x) is linear on each side of x = 0, with slopes u'(x) = A on the left and u'(x) = B on the right:

$$u(x) = \begin{cases} Ax & \text{for } x \le 0\\ Bx & \text{for } x \ge 0 \end{cases}$$

What is the second derivative u''(x)? Give the answer at every x.

(b) Take discrete values  $U_n$  at all the whole numbers x = n:

$$U_n = \begin{cases} An & \text{for } n \le 0\\ Bn & \text{for } n \ge 0 \end{cases}$$

For each n, what is the second difference  $\Delta^2 U_n$ ? Using coefficients 1, -2, 1 (notice signs!) give the answer  $\Delta^2 U_n$  at every n.

- (c) Solve the differential equation  $-u''(x) = \delta(x)$  from x = -2 to x = 3with boundary values u(-2) = 0 and u(3) = 0.
- (d) Approximate problem (c) by a difference equation with  $h = \Delta x = 1$ . What is the matrix in the equation KU = F? What is the solution U?

Solutions.

(a) 
$$u''(x) = (B - A) \,\delta(x)$$
. This is not  $B - A$  at  $x = 0$ .  
(b)  $\Delta^2 u_n = \begin{cases} B - A & n = 0 \\ 0 & n \neq 0 \end{cases}$   
(c)  $u(x) = \begin{cases} 3/5 \, (x + 2) & -2 \le x \le 0 \\ 2/5 \, (3 - x) & 0 \le x \le 3 \end{cases}$   
(d)  $K_{+++} = \begin{bmatrix} 2 & -1 & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{bmatrix} \quad U = \begin{bmatrix} 3/5 \\ 6/5 \\ 4/5 \\ 2/5 \end{bmatrix}$  fixed-fixed

U lies right on the graph of u(x)

- 2) (24 pts.) A symmetric matrix K is "positive definite" if  $u^{T}Ku > 0$  for every nonzero vector u.
- (a) Suppose K is positive definite and u is a (nonzero) eigenvector, so  $Ku = \lambda u$ . From the definition above show that  $\lambda > 0$ . What solution u(t) to  $\frac{du}{dt} = Ku$  comes from knowing this eigenvector and eigenvalue?
- (b) Our second-difference matrix  $K_4$  has the form  $A^{\mathrm{T}}A$ :

$$K_4 = \begin{bmatrix} 1 & -1 & & \\ & 1 & -1 & \\ & & 1 & -1 \\ & & & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ -1 & 1 & & \\ & -1 & 1 & \\ & & -1 & 1 \\ & & & -1 \end{bmatrix} = \begin{bmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{bmatrix}$$

Convince me how  $K_4 = A^{\mathrm{T}}A$  proves that  $u^{\mathrm{T}}K_4 u = u^{\mathrm{T}}A^{\mathrm{T}}A u > 0$  for every nonzero vector u. (Show me why  $u^{\mathrm{T}}A^{\mathrm{T}}A u \ge 0$  and why > 0.)

(c) This matrix is positive definite for which b? Semidefinite for which b? What are its pivots??

$$S = \begin{bmatrix} 2 & b \\ b & 4 \end{bmatrix}$$

Solutions. (8 pts each)

(a) "... show that  $\lambda > 0$ "

$$\begin{aligned} Ku &= \lambda u \\ u^{\mathrm{T}} Ku &= \lambda u^{\mathrm{T}} u \end{aligned} \quad \text{so} \quad \lambda = \frac{u^{\mathrm{T}} Ku}{u^{\mathrm{T}} u} > 0 \end{aligned}$$

"What solution  $u(t) \dots$ "

$$u(t) = e^{\lambda t} u$$

(b) 
$$u^{\mathrm{T}}A^{\mathrm{T}}Au = (Au)^{\mathrm{T}}(Au) \ge 0$$

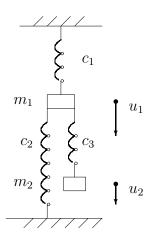
The particular matrix A in this problem has independent columns. The only solution to Au = 0 is u = 0. So  $u^{T}A^{T}Au > 0$  except when u = 0. Other proofs are *possible*.

(c) Positive definite if  $b^2 < 8$ 

Semidefinite if  $b^2 = 8$ 

Pivots 2 and  $4 - \frac{b^2}{2}$ 

3) (40 pts.) (a) Suppose I measure (with possible error) u<sub>1</sub> = b<sub>1</sub> and u<sub>2</sub> - u<sub>1</sub> = b<sub>2</sub> and u<sub>3</sub> - u<sub>2</sub> = b<sub>3</sub> and finally u<sub>3</sub> = b<sub>4</sub>. What matrix equation would I solve to find the best least squares estimate û<sub>1</sub>, û<sub>2</sub>, û<sub>3</sub>? Tell me the matrix and the right side in Kû = f.



- (b) What 3 by 2 matrix A gives the spring stretching e = A u from the displacements  $u_1, u_2$  of the masses?
- (c) Find the stiffness matrix  $K = A^{T}CA$ . Assuming positive  $c_1, c_2, c_3$  show that K is invertible and positive definite.

## Solutions.

(a) (12 points)

 $Au = b \qquad \text{is} \qquad \begin{bmatrix} 1 & & \\ -1 & 1 & \\ & -1 & 1 \\ & & 1 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$  $\underbrace{A^{\mathrm{T}}A}_{K} \hat{u} = \underbrace{A^{\mathrm{T}}b}_{f} \qquad \text{is} \qquad \underbrace{\begin{bmatrix} 2 & -1 \\ -1 & 2 & -1 \\ -1 & 2 \end{bmatrix}}_{K} \begin{bmatrix} \hat{u}_1 \\ \hat{u}_2 \\ \hat{u}_3 \end{bmatrix} = \underbrace{\begin{bmatrix} b_2 - b_1 \\ b_3 - b_2 \\ b_4 + b_3 \end{bmatrix}}_{f}$  $\underbrace{K}_{3pts \ for numbers} \qquad \underbrace{K}_{3pts \ for numbers} \qquad \underbrace{K}_{3pts}$ 

(b) (10 points) 
$$A = \begin{bmatrix} 1 & 0 \\ -1 & 0 \\ -1 & 1 \end{bmatrix}$$

(c) (16 points) 
$$A^{\mathrm{T}}CA = \begin{bmatrix} 1 & -1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 & & \\ & c_2 & \\ & & & c_3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -1 & 0 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} c_1 + c_2 + c_3 & -c_3 \\ -c_3 & & c_3 \end{bmatrix}$$

Any of these proofs is OK:

(1) det = 
$$c_1c_3 + c_2c_3 > 0$$

- (2)  $A^{\mathrm{T}}CA$  always positive definite with independent columns in A
- (3) other ideas ...