18.034 Honors Differential Equations Spring 2009

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.

18.034 Problem Set #8

(modified on April 27, 2009)

Due by Friday, May 1, 2009, by NOON.

1. An $n \times n$ complex matrix A is called *Hermitian* if $A = A^*$, where A^* is the conjugate transpose of A. That is, $a_{ij} = \overline{a}_{ji}$ for all $1 \le i, j \le n$. When A is real $A^* = A^T$ and the terms "Hermitian" and "symmetric" mean the same thing. If $\vec{u} = (u_1, \ldots, u_n)$ and $\vec{v} = (v_1, \ldots, v_n)$ are column vectors in \mathbb{R}^n , then $\vec{u}\vec{v}^* = u_1\bar{v}_1 + \cdots + u_n\bar{v}_n$ and $||u||^2 = uu^*$.

If $A = A^*$ show that all eienvalues of A are real. Furthermore, if $A = A^*$ then eigenvectors \vec{u} and \vec{v} corresponding to different eigenvalues λ and μ are orthogonal. That is, $\vec{u}\vec{v}^* = 0$.

2. If *A* and *B* are $n \times n$ matrices, compute

$$\lim_{t \to 0} \frac{e^{At} e^{Bt} - e^{Bt} e^{At}}{t^2}$$

3. (a) Let *A* be a 3×3 matrix with eigenvalues $\lambda_1, \lambda_2, \lambda_3$. Show that the nonzero columns of $(A - \lambda_2 I)(A - \lambda_3 I)$ are eigenvectors for λ_1 .

(b) A 3 × 3 matrix A has characteristic polynomial $p(\lambda) = \lambda(\lambda^2 - 1)$. Find e^{At} .

4. (a) For x' = 6x + y, y' = 4x + 3y show that the origin is an unstable node.

(b) If y = mx is a trajectory, show that m = 1 or m = -4.

(c) Sketch the trajectories in the (x, y)-plane.

5. Repeat Problem 4 for x' = -3x + 2y, y' = -3x + 4y.

6. Consider the differential equation u'' + p(t)u' + q(t)u = 0, where p(t), q(t) are continuous functions on some interval of *t*.

(a) Let

$$u(t) = r(t)\sin\theta(t), \qquad u'(t) = r(t)\cos\theta(t).$$

Show that

$$d\theta/dt = \cos^2 \theta + p(t)\cos\theta\sin\theta + q(t)\sin^2\theta,$$

(1/r)dr/dt = -p(t) cos² \theta + (1 - q(t)) cos \theta sin \theta.

(b) Using part (a) discuss that if $q(t) > p^2(t)/4$ then solutions are *oscillatory* and if q(t) < 0 then solutions are *nonoscillatory*.