## 2. Dot product

**Definition 2.1.** Let  $\vec{v} = (v_1, v_2, v_3)$  and  $\vec{w} = (w_1, w_2, w_3)$  be two vectors in  $\mathbb{R}^3$ . The **dot product** of  $\vec{v}$  and  $\vec{w}$ , denoted  $\vec{v} \cdot \vec{w}$ , is the scalar  $v_1w_1 + v_2w_2 + v_3w_3$ .

**Example 2.2.** The dot product of  $\vec{v} = (1, -2, -1)$  and  $\vec{w} = (2, 1, -3)$  is

$$1 \cdot 2 + (-2) \cdot 1 + (-1) \cdot (-3) = 2 - 2 + 3 = 3.$$

**Lemma 2.3.** Let  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$  be three vectors in  $\mathbb{R}^3$  and let  $\lambda$  be a scalar.

- $(1) \ (\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w}.$
- (2)  $\vec{v} \cdot \vec{w} = \vec{w} \cdot \vec{v}$ .
- (3)  $(\lambda \vec{v}) \cdot \vec{w} = \lambda (\vec{v} \cdot \vec{w}).$
- (4)  $\vec{v} \cdot \vec{v} = 0$  if and only if  $\vec{v} = \vec{0}$ .

*Proof.* (1–3) are straightforward.

To see (4), first note that one direction is clear. If  $\vec{v} = \vec{0}$ , then  $\vec{v} \cdot \vec{v} = 0$ . For the other direction, suppose that  $\vec{v} \cdot \vec{v} = 0$ . Then  $v_1^2 + v_2^2 + v_3^2 = 0$ . Now the square of a real number is non-negative and if a sum of non-negative numbers is zero, then each term must be zero. It follows that  $v_1 = v_2 = v_3 = 0$  and so  $\vec{v} = \vec{0}$ .

**Definition 2.4.** If  $\vec{v} \in \mathbb{R}^3$ , then the **norm** or **length** of  $\vec{v} = (v_1, v_2, v_3)$  is the scalar

$$||v|| = \sqrt{\vec{v} \cdot \vec{v}} = (v_1^2 + v_2^2 + v_3^2)^{1/2}.$$

It is interesting to note that if you know the norm, then you can calculate the dot product:

$$(\vec{v} + \vec{w}) \cdot (\vec{v} + \vec{w}) = \vec{v} \cdot \vec{v} + 2\vec{v} \cdot \vec{w} + \vec{w} \cdot \vec{w}$$

$$(\vec{v} - \vec{w}) \cdot (\vec{v} - \vec{w}) = \vec{v} \cdot \vec{v} - 2\vec{v} \cdot \vec{w} + \vec{w} \cdot \vec{w}.$$

Subtracting and dividing by 4 we get

$$\vec{v} \cdot \vec{w} = \frac{1}{4} \left( (\vec{v} + \vec{w}) \cdot (\vec{v} + \vec{w}) - (\vec{v} - \vec{w}) \cdot (\vec{v} - \vec{w}) \right)$$
$$= \frac{1}{4} (\|\vec{v} + \vec{w}\|^2 - \|\vec{v} - \vec{w}\|^2).$$

Given two non-zero vectors  $\vec{v}$  and  $\vec{w}$  in space, note that we can define the angle  $\theta$  between  $\vec{v}$  and  $\vec{w}$ .  $\vec{v}$  and  $\vec{w}$  lie in at least one plane (which is in fact unique, unless  $\vec{v}$  and  $\vec{w}$  are parallel). Now just measure the angle  $\theta$  between the  $\vec{v}$  and  $\vec{w}$  in this plane. By convention we always take  $0 < \theta < \pi$ .

**Theorem 2.5.** If  $\vec{v}$  and  $\vec{w}$  are any two vectors in  $\mathbb{R}^3$ , then

$$\vec{v} \cdot \vec{w} = ||\vec{v}|| \ ||\vec{w}|| \cos \theta.$$

*Proof.* If  $\vec{v}$  is the zero vector, then both sides are equal to zero, so that they are equal to each other and the formula holds (note though, that in this case the angle  $\theta$  is not determined).

By symmetry, we may assume that  $\vec{v}$  and  $\vec{w}$  are both non-zero. Let  $\vec{u} = \vec{w} - \vec{v}$  and apply the law of cosines to the triangle with sides parallel to  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$ :

$$\|\vec{u}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2 - 2\|\vec{v}\| \|\vec{w}\| \cos \theta.$$

We have already seen that the LHS of this equation expands to

$$\vec{v} \cdot \vec{v} - 2\vec{v} \cdot \vec{w} + \vec{w} \cdot \vec{w} = ||\vec{v}||^2 - 2\vec{v} \cdot \vec{w} + ||\vec{w}||.$$

Cancelling the common terms  $\|\vec{v}\|^2$  and  $\|\vec{w}\|^2$  from both sides, and dividing by 2, we get the desired formula.

We can use (2.5) to find the angle between two vectors:

**Example 2.6.** Let  $\vec{v} = -\hat{\imath} + \hat{k}$  and  $\vec{w} = \hat{\imath} + \hat{\jmath}$ . Then

$$-1 = \vec{v} \cdot \vec{w} = ||\vec{v}|| ||\vec{w}|| \cos \theta = 2 \cos \theta.$$

Therefore  $\cos \theta = -1/2$  and so  $\theta = 2\pi/3$ .

**Definition 2.7.** We say that two vectors  $\vec{v}$  and  $\vec{w}$  in  $\mathbb{R}^3$  are **orthogonal** if  $\vec{v} \cdot \vec{w} = 0$ .

**Remark 2.8.** If neither  $\vec{v}$  nor  $\vec{w}$  are the zero vector, and  $\vec{v} \cdot \vec{w} = 0$  then the angle between  $\vec{v}$  and  $\vec{w}$  is a right angle. Our convention is that the zero vector is orthogonal to every vector.

**Example 2.9.**  $\hat{\imath}$ ,  $\hat{\jmath}$  and  $\hat{k}$  are pairwise orthogonal.

Given two vectors  $\vec{v}$  and  $\vec{w}$ , we can project  $\vec{v}$  onto  $\vec{w}$ . The resulting vector is called the **projection** of  $\vec{v}$  onto  $\vec{w}$  and is denoted  $\operatorname{proj}_{\vec{w}} \vec{v}$ . For example, if  $\vec{F}$  is a force and  $\vec{w}$  is a direction, then the projection of  $\vec{F}$  onto  $\vec{w}$  is the force in the direction of  $\vec{w}$ .

As  $\operatorname{proj}_{\vec{w}} \vec{v}$  is parallel to  $\vec{w}$ , we have

$$\operatorname{proj}_{\vec{w}} \vec{v} = \lambda \vec{w},$$

for some scalar  $\lambda$ . Let's determine  $\lambda$ . Let's deal with the case that  $\lambda \geq 0$  (so that the angle  $\theta$  between  $\vec{v}$  and  $\vec{w}$  is between 0 and  $\pi/2$ ). If we take the norm of both sides, we get

$$\|\operatorname{proj}_{\vec{w}} \vec{v}\| = \|\lambda \vec{w}\| = \lambda \|\vec{w}\|,$$

(note that  $\lambda \geq 0$ ), so that

$$\lambda = \frac{\|\operatorname{proj}_{\vec{w}} \vec{v}\|}{\|\vec{w}\|}.$$

But

$$\cos \theta = \frac{\|\operatorname{proj}_{\vec{w}} \vec{v}\|}{\|\vec{v}\|},$$

so that

$$\|\operatorname{proj}_{\vec{w}} \vec{v}\| = \|\vec{v}\| \cos \theta.$$

Putting all of this together we get

$$\lambda = \frac{\|\vec{v}\| \cos \theta}{\|\vec{w}\|}$$

$$= \frac{\|\vec{v}\| \|\vec{w}\| \cos \theta}{\|\vec{w}\|^2}$$

$$= \frac{\vec{v} \cdot \vec{w}}{\|\vec{w}\|^2}.$$

There are a number of ways to deal with the case when  $\lambda < 0$  (so that  $\theta > \pi/2$ ). One can carry out a similar analysis to the one given above. Here is another way. Note that the angle  $\phi$  between  $\vec{w}$  and  $\vec{u} = -\vec{v}$  is equal to  $\pi - \theta < \pi/2$ . By what we already proved

$$\operatorname{proj}_{\vec{w}} \vec{u} = \frac{\vec{u} \cdot \vec{w}}{\|\vec{w}\|^2} \vec{w}.$$

But  $\operatorname{proj}_{\vec{w}} \vec{u} = -\operatorname{proj}_{\vec{w}} \vec{v}$  and  $\vec{u} \cdot \vec{w} = -\vec{v} \cdot \vec{w}$ , so we get the same formula in the end. To summarise:

**Theorem 2.10.** If  $\vec{v}$  and  $\vec{w}$  are two vectors in  $\mathbb{R}^3$ , where  $\vec{w}$  is not zero, then

$$\operatorname{proj}_{\vec{w}} \vec{v} = \left(\frac{\vec{v} \cdot \vec{w}}{\|\vec{w}\|^2}\right) \vec{w}.$$

**Example 2.11.** Find the distance d between the line l containing the points  $P_1 = (1, -1, 2)$  and  $P_2 = (4, 1, 0)$  and the point Q = (3, 2, 4).

Suppose that R is the closest point on the line l to the point Q. Note that  $\overrightarrow{QR}$  is orthogonal to the direction  $\overrightarrow{P_1P_2}$  of the line. So we want the length of the vector  $\overrightarrow{P_1Q} - \operatorname{proj}_{\overrightarrow{P_1P_2}} \overrightarrow{P_1Q}$ , that is, we want

$$d = \|\overline{P_1}Q - \operatorname{proj}_{\overline{P_1P_2}} \overline{P_1}Q\|.$$

Now

$$\overrightarrow{P_1Q} = (2, 3, 2)$$
 and  $\overrightarrow{P_1P_2} = (3, 2, -2).$ 

We have

$$\|\overrightarrow{P_1P_2}\|^2 = 3^2 + 2^2 + 2^2 = 17$$
 and  $\overrightarrow{P_1P_2} \cdot \overrightarrow{P_1Q} = 6 + 6 - 4 = 8.$ 

It follows that

$$\operatorname{proj}_{\overrightarrow{P_1P_2}}\overrightarrow{P_1Q} = \frac{8}{17}(3,2,-2).$$

Subtracting, we get

$$\overrightarrow{P_1Q} - \text{proj}_{\overrightarrow{P_1P_2}} \overrightarrow{P_1Q} = (2,3,2) - \frac{8}{17}(3,2,-2) = \frac{1}{17}(10,35,50) = \frac{5}{17}(2,7,10).$$

Taking the length, we get

$$\frac{5}{17}(2^2 + 7^2 + 10^2)^{1/2} \approx 3.64.$$

**Theorem 2.12.** The angle subtended on the circumference of a circle by a diameter of the circle is always a right angle.

*Proof.* Suppose that P and Q are the two endpoints of a diameter of the circle and that R is a point on the circumference. We want to show that the angle between  $\overrightarrow{PR}$  and  $\overrightarrow{QR}$  is a right angle.

Let O be the centre of the circle. Then

$$\overrightarrow{PR} = \overrightarrow{PO} + \overrightarrow{OR}$$
 and  $\overrightarrow{QR} = \overrightarrow{QO} + \overrightarrow{OR}$ .

Note that  $\overrightarrow{QO} = -\overrightarrow{PO}$ . Therefore

$$\overrightarrow{PR} \cdot \overrightarrow{QR} = (\overrightarrow{PO} + \overrightarrow{OR}) \cdot (\overrightarrow{QO} + \overrightarrow{OR})$$

$$= (\overrightarrow{PO} + \overrightarrow{OR}) \cdot (\overrightarrow{OR} - \overrightarrow{PO})$$

$$= ||\overrightarrow{OR}||^2 - ||\overrightarrow{PO}||^2$$

$$= r^2 - r^2 = 0,$$

where r is the radius of the circle. It follows that  $\overrightarrow{PR}$  and  $\overrightarrow{QR}$  are indeed orthogonal.

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