

Review of Temporal Logic and Buchi Automata

Computer Science and Artificial Intelligence Laboratory

MIT

Armando Solar-Lezama

Nov 25, 2015

CTL* Logic

Add two extra path quantifiers

- $A f$:= for all paths, f
- $E f$:= for some path, f

Two important subsets:

- LTL : all formulas of the form $A f$
 - Ex: $A(FG p)$
- CTL: there must be a path quantifier before every linear operator
 - Ex: $AG (EF p)$
- The two are different!

Example:

What does the following formula mean

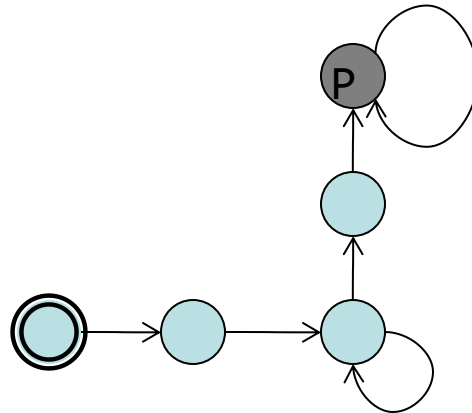
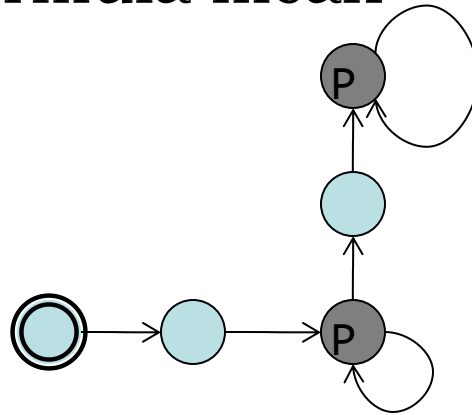
- $A(F G p)$

How about

- $A(F A G p)$

How about

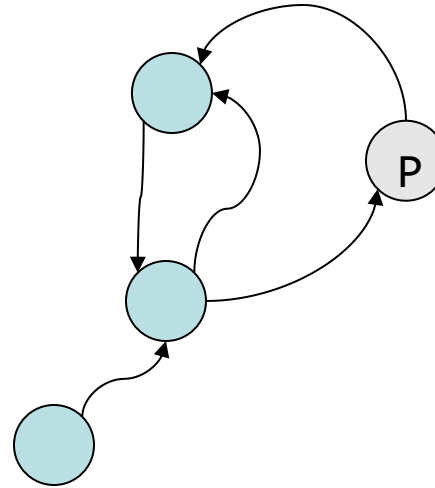
- $A(F E G p)$



Review of Temporal Logic

What about the following formula:

- $AG \ EF \ p$



Review of Temporal Logic

What does the following formula mean

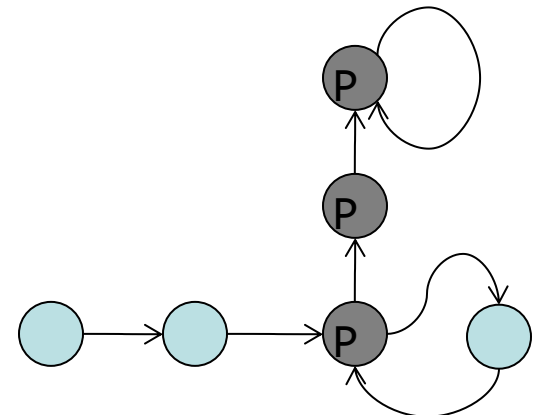
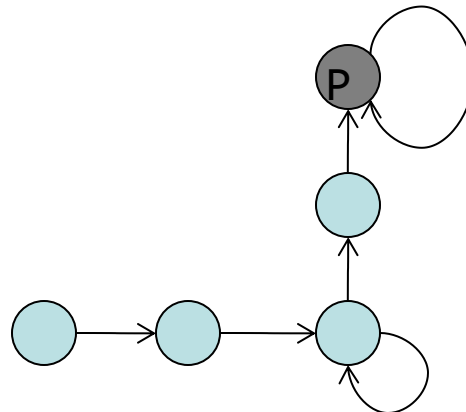
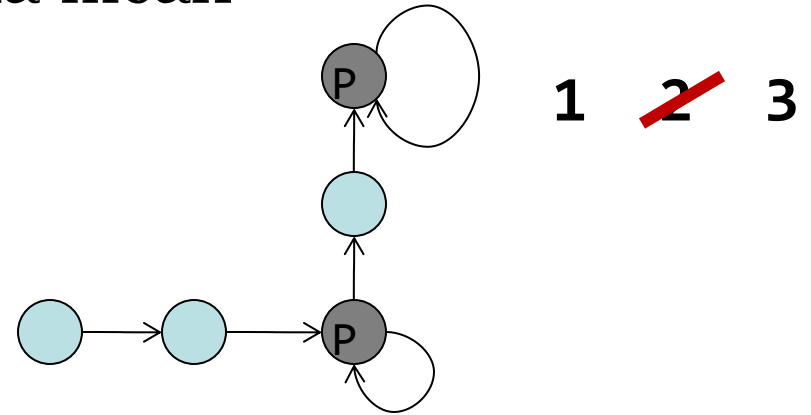
1) $A(F G p)$

How about

2) $A(F A G p)$

How about

3) $A(F E G p)$



History Lesson

“Sometimes” and “Not Never” Revisited: On Branching versus Linear Time Temporal Logic

- [Allen Emerson and Joseph Y. Halpern JACM Vol 33, 1986](#)

Introduces CTL* as a way to unify branching time and linear time logics

Review of Temporal Logic

From any state, it is possible to return to the reset state along some execution.

- AGEF reset

A request should stay asserted until an acknowledge is received. The acknowledge must eventually be received.

- $G \text{ req} \rightarrow \text{req} U \text{ ack}$

And, Ack must be received three cycles after request

- $G \text{ req} \rightarrow (\text{req} U \text{ ack} \wedge \text{XXX ack})$

Review of Temporal Logic



© MotorTrend Magazine TEN: The Enthusiast Network. All rights reserved. This content is excluded from our Creative Commons license. For more information, see <http://ocw.mit.edu/help/faq-fair-use/>.

Engine starts and stops with button push

- If engine is off, it stays off until I push
 - If I never push it stays off forever
- If engine is on, it stays on until I push
 - If I never push it stays on forever
- If the engine is on, I should be able to stop it at any moment
- If it is off, I should be able to turn it back on, but not without identifying myself

on, off, push, id

$G \text{ off} \Rightarrow \text{off } U \text{ push}$

$G (\text{off} \Rightarrow (\text{off } U \text{ push} \vee G \text{ off}))$

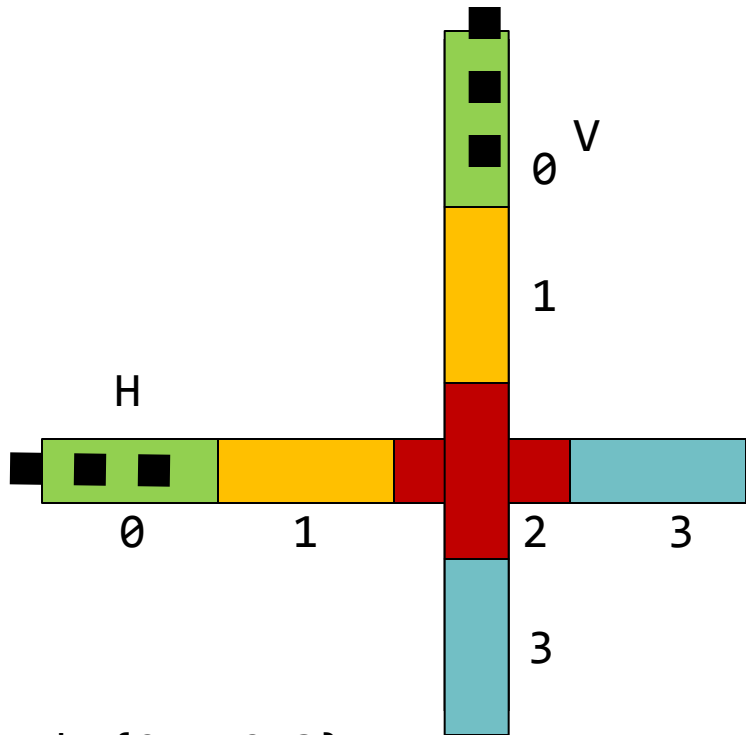
$G (\text{on} \Rightarrow (\text{on } U \text{ push} \vee G \text{ on}))$

$AG (\text{on} \Rightarrow EF \text{ off})$

$AG (\text{off} \Rightarrow (EF \text{ on}) \wedge A((\text{off } U \text{ id}) \vee G \text{ off}))$

$A((\text{off } U \text{ id}) \vee G \text{ off}) \equiv \neg E(\neg \text{id } U (\neg \text{off} \wedge \neg \text{id}))$

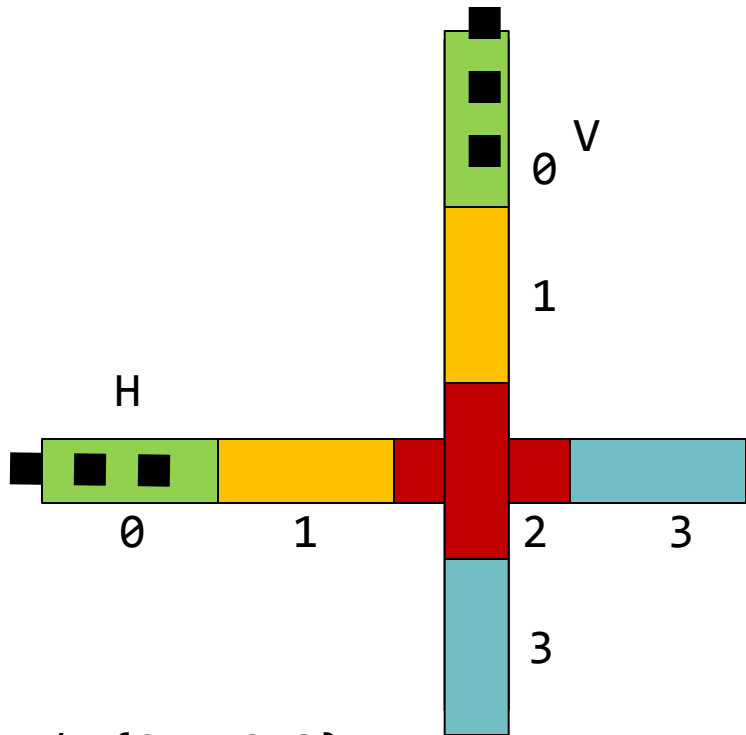
Can the trains collide? $\neg F (ph = 2 \wedge pv = 2)$



$ph = \{0, 1, 2, 3\}$
 $pv = \{0, 1, 2, 3\}$
 $g = \{h, v, free\}$
 $pch = \{0, 1, \dots, 9\}$
 $pcv = \{0, 1, \dots, 9\}$

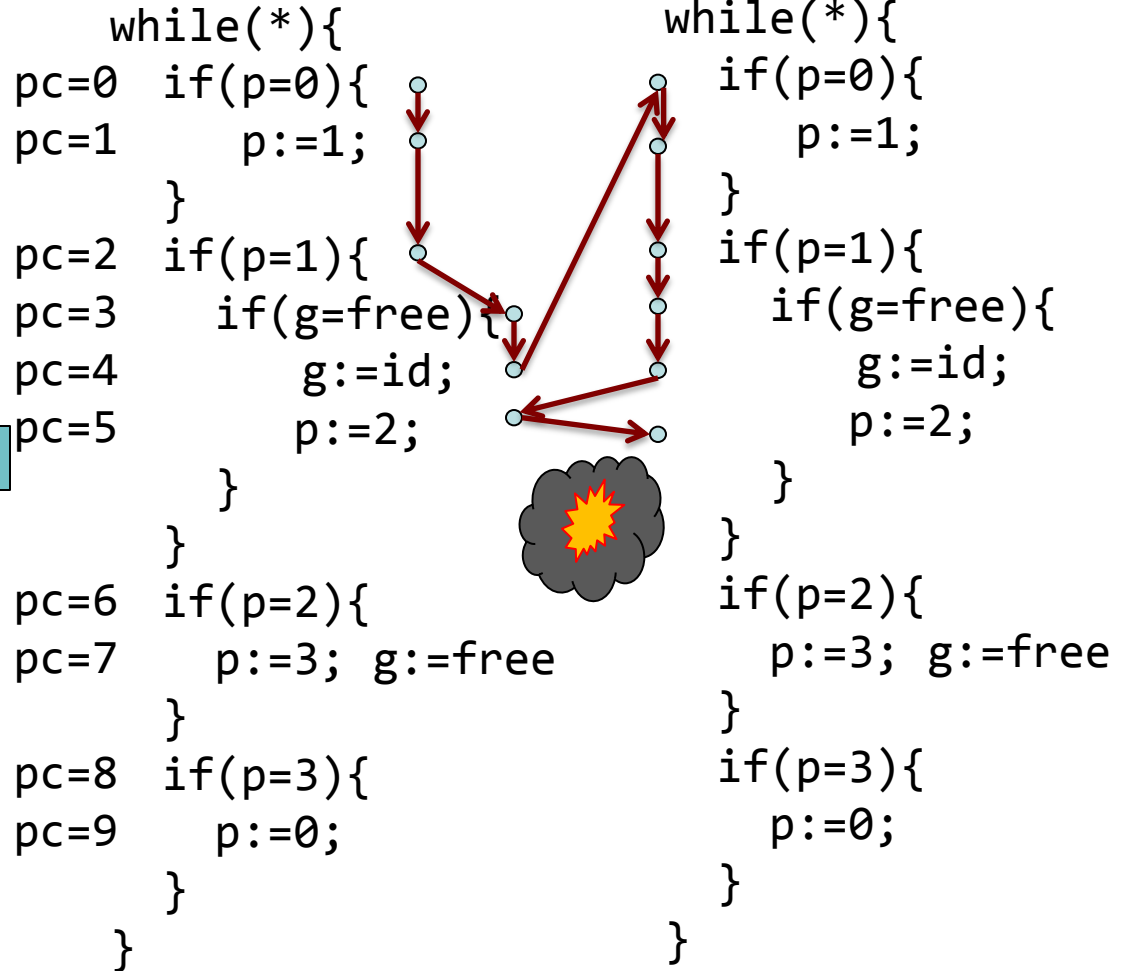
```
pc=0      while(*){
pc=1      if(p=0){
          p:=1;
          }
pc=2      if(p=1){
pc=3      if(g=free){
pc=4      g:=id;
pc=5      p:=2;
          }
          }
pc=6      if(p=2){
pc=7      p:=3; g:=free;
          }
pc=8      if(p=3){
pc=9      p:=0;
          }
          }
```

Can the trains collide? $\neg F (ph = 2 \wedge pv = 2)$



$ph = \{0, 1, 2, 3\}$
 $pv = \{0, 1, 2, 3\}$
 $g = \{h, v, \text{free}\}$
 $pch = \{0, 1, \dots, 9\}$
 $pcv = \{0, 1, \dots, 9\}$

(ph, pv, g, pch, pcv)



H train

V train

Liveness Vs. Safety

Two terms you are likely to run into:

Safety:

- Something bad will never happen: $G \neg bad$
- If it fails to hold, it's easy to produce a witness

Liveness:

- Something good will eventually happen: $F good$
- What does a witness for this look like?

Automata for LTL properties

LTL defines properties over a trace

Given a trace, we want to know whether it satisfies the property

Problem:

- we need to build an automata to recognize infinite strings!
- ω – *Regular Languages*

Buchi Automata

Similar to a DFA

- but with a stronger notion of acceptance

In DFA, you have an accept state

- when you reach accept state, you are done
- this means you only accept finite strings

In Buchi automata you also have accepting states

- but you only accept strings that visit the accept state infinitely often

Buchi Automata

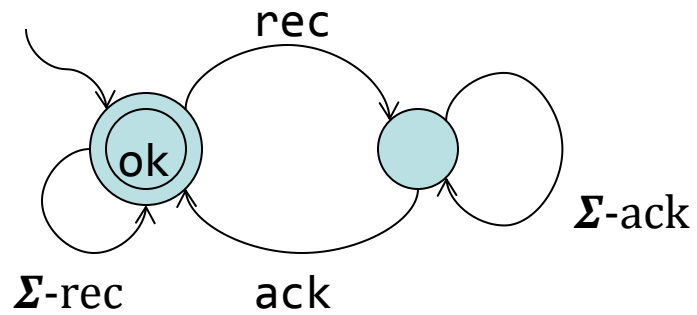
A Buchi Automaton is a 5-tuple $\langle \Sigma, S, I, \delta, F \rangle$

- Σ is an alphabet
- S is a finite set of states
- $I \subseteq S$ is a set of initial states
- $\delta \subseteq S \times \Sigma \times S$ is a transition relation
- $F \subseteq S$ is a set of accepting states

Non-deterministic Buchi Automata are not equivalent to deterministic ones

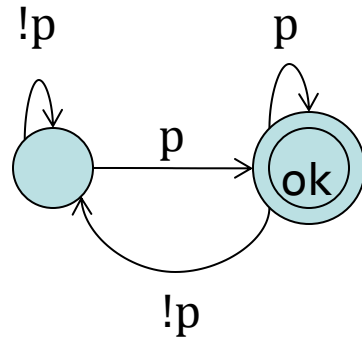
Example

$G \text{ req} \rightarrow F \text{ ack}$



Example

$G \models F p$



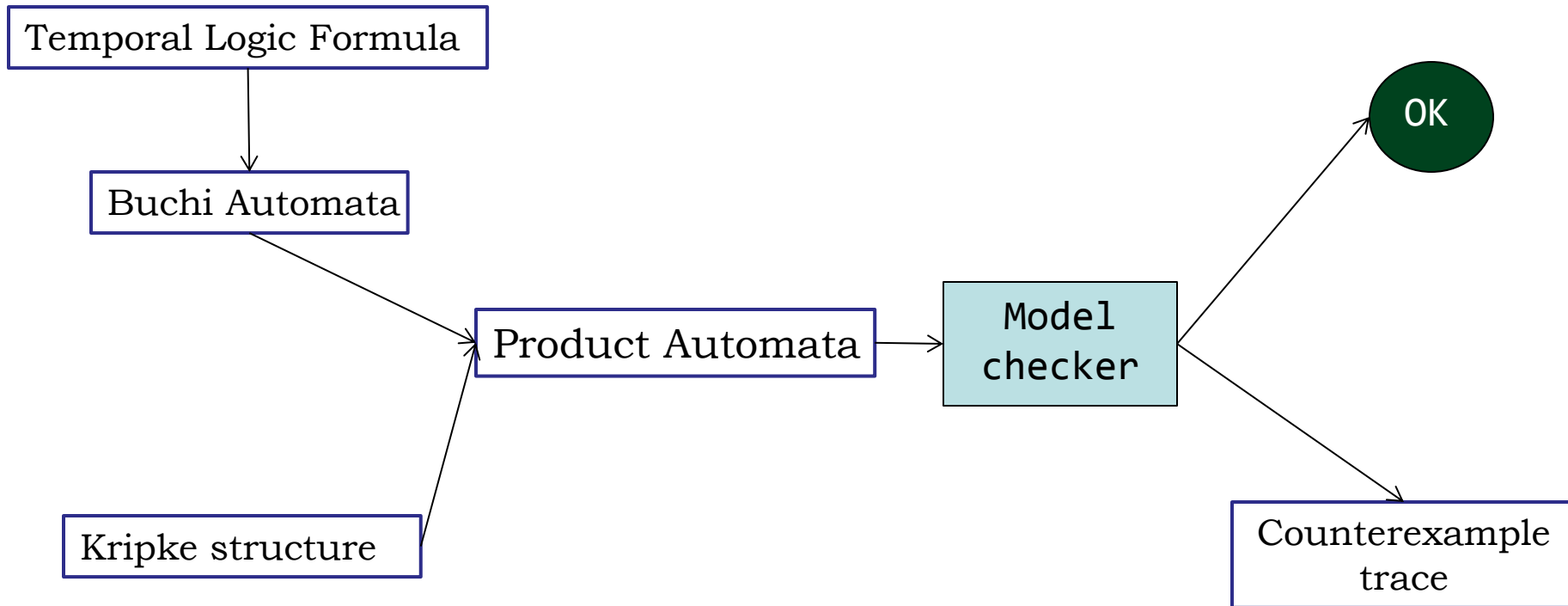
From LTL to automata

Any LTL formula can be expressed as a buchi automata

- but the construction of the automata is complicated
 - exponential on the size of the formula
- See Vardi and Wolper, *Reasoning about infinite computations*, 1983

Explicit State Model checking

The basic Strategy



MIT OpenCourseWare
<http://ocw.mit.edu>

6.820 Fundamentals of Program Analysis
Fall 2015

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.