# **Practice Problems 1**

#### Problem 1-1. Sub-linear time algorithms

- (a) Given a string of 0's and 1's of size n, design an algorithm as efficient as possible that estimates the fraction of 1's in the string up to an additive  $\epsilon n$ .
- (b) Extend the minimum spanning tree sub-linear time algorithm to handle real weights between 1 and w.

## Problem 1-2. Pseudorandom Path of Length k

In recitation we considered the problem of finding a simple path with k edges in a given graph. We saw a randomized algorithm for this problem:

- Repeat the following 100k! times:
  - 1. Pick a random order on the vertices. Remove all edges that go backwards.
  - 2. Use dynamic programming to find the longest simple path in the graph. If it has at least k edges, return a sub-path with k edges.

Derandomize this algorithm using a "k-wise independent hash family." This is a hash family  $H = \{h : V \to \{1, ..., k\}\}$  such that for every different  $v_1, ..., v_k$  and every vector b in  $\{1, ..., k\}^k$ , the probability that a random  $h \in H$  satisfies  $h(v_1) = b_1 \land ... \land h(v_k) = b_k$  is  $k^{-k}$ .

## Problem 1-3. Polynomial testing

It can be proved that an *m*-variate polynomial  $P(x_1, \ldots, x_m)$  of total degree at most *D* that is not identically 0 has at most  $Dp^{m1}$  zeros modulo *p* in any set of inputs of the form  $Z_p^m$  for a prime *p* (recall that  $Z_p = 0, ..., p - 1$ ).

Show how to find, given the coefficients of P, a point  $(x_1, \ldots, x_m)$  that is a non-zero of P:

- (a) Devise a randomized algorithm.
- (b) Use the method of conditional expectations to find a deterministic algorithm.

### **Problem 1-4. Computational Geometry**

- (a) (CLRS Exercise 33.2-6) A *disk* consists of a circle plus its interior and is represented by its center point and radius. Two disks intersect if they have any point in common. Give an  $O(n \lg n)$  time algorithm to determine whether any two disks in a set of n intersect.
- (b) (CLRS Exercise 33.4-4) Given two points  $p_1$  and  $p_2$  in the plane, the  $L_{\infty}$ -distance between them is given by  $\max(|x_1 x_2|, |y_1 y_2|)$ . Modify the closest-pair algorithm to use the  $L_{\infty}$ -distance.

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