3 Spatial Averaging

♦ 3-D equations of motion Scaling => simplifications Spatial averaging Shear dispersion Magnitudes/time scales of diffusion/dispersion Examples

Navier-Stokes Eqns

Conservative form momentum eqn; x-component only



3 4

5

1 "storage" or local acceleration

2

2 advective acceleration

3 Coriolis acceleration [f = Coriolis param = $2\omega \sin(\theta)$, θ = latitude]

- 4 pressure gradient
- 5 viscous stress

1

Turbulent Reynolds Eqns



Specific terms

Term 2a: could subtract \overline{u} times continuity eqn

 $\overline{u}\frac{\partial\overline{u}}{\partial x} + \overline{v}\frac{\partial\overline{u}}{\partial x} + \overline{w}\frac{\partial\overline{u}}{\partial x}$ NC form of momentum eqn (term 2)

Terms 5 + 2b

x-comp of turbulent shear stress

 $\upsilon \frac{\partial \overline{u}}{\partial x} - \overline{u'^2} = \tau_{xx} \cong -\overline{u'^2} \cong 2\varepsilon_{xx} \frac{\partial \overline{u}}{\partial x}$ $\upsilon \frac{\partial \overline{u}}{\partial y} - \overline{u'v'} = \tau_{xy} \cong -\overline{u'v'} \cong \varepsilon_{xy} \left(\frac{\partial \overline{u}}{\partial y} + \frac{\partial \overline{v}}{\partial x}\right)$

 $=\overline{u}\left[\frac{\partial\overline{u}}{\partial x} + \frac{\partial\overline{v}}{\partial y} + \frac{\partial\overline{w}}{\partial z}\right]$

 $\upsilon \frac{\partial \overline{u}}{\partial z} - \overline{u'w'} = \tau_{xz} \cong -\overline{u'w'} \cong \mathcal{E}_{xz} \left(\frac{\partial \overline{u}}{\partial z} + \frac{\partial \overline{w}}{\partial x} \right)$

 ϵ_{xx} , ϵ_{xy} , ϵ_{xz} are turbulent (eddy) kinematic viscosities resulting from closure model (like E_{xx} , E_{xy} , E_{xz})

Specific terms, cont'd

Similar eqns for y and z except z has gravity.

For nearly horizontal flow (w \sim 0), z-mom => hydrostatic



Use in x and y eqns

Specific terms, cont'd

Term 4



- 4a atmospheric pressure gradient (often negligible)
- 4b barotropic pressure gradient (barotropic => $\rho = \rho_s = const$)
- 4c baroclinic pressure gradient (baroclinic => density gradients; often negligible)

Simplification

Neglect ε_{xx} ; $\varepsilon_{xy} = \varepsilon_h$; $\varepsilon_{zx} = \varepsilon_z$ Neglect all pressure terms except barotropic And drop over bars $\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(u^2) + \frac{\partial}{\partial y}(uv) + \frac{\partial}{\partial z}(uw) - fv = -g\frac{\partial\eta}{\partial x} + \frac{\partial}{\partial y}\left(\varepsilon_h\frac{\partial u}{\partial y}\right) + \frac{\partial}{\partial z}\left(\varepsilon_z\frac{\partial u}{\partial z}\right)$ 2a 3 4b 2b1 2b2 Contrast with mass transport eqn $\frac{\partial \overline{c}}{\partial t} + \frac{\partial}{\partial x}(uc) + \frac{\partial}{\partial y}(vc) + \frac{\partial}{\partial z}(wc) = \frac{\partial}{\partial x}\left(E_x\frac{\partial c}{\partial y}\right) + \frac{\partial}{\partial y}\left(E_y\frac{\partial c}{\partial y}\right) + \frac{\partial}{\partial z}\left(E_z\frac{\partial c}{\partial z}\right) \pm \sum r$ 2a2b1 1 2b2 7

Pressure gradient (4) in momentum eqn => viscosity (2b) not always important to balance advection (2a); depends on shear (separation). For mass transport, diffusivity (2b) always needed to balance advection (2a)

Comments

 3D models include continuity + three components of momentum eq (z may be hydrostatic approx) + n mass transport eqns
 Above are primitive eqs (u, v, w); sometimes different form, but physics should be same
 Sometimes further simplifications
 Spatial averaging => reduced dimensions

Further possible simplifications

Neglect terms 2a and 2b1



Also neglect term 1



Also neglect term 2b2



Linear shallow water wave eqn

Steady Ekman flow

Geostrophic flow



Comments

 Models of reduced dimension achieved by spatial averaging or direct formulation (advantages of both)

 Demonstration of vertical averaging (integrate over depth then divide by depth, leading to 2D depth-averaged models)
 Discussion of cross-sectional averaging (river models)

Vertical Integration => 2D (depth-averaged) eqns

X



Vertical Integration, cont'd



$$\overline{\overline{u}}(x, y, t) = \frac{1}{H} \int_{u} u(x, y, z, t) dz$$

1 n

In analogy with Reynolds averaging, decompose velocities and concentrations into $\overline{u} + u''$, $\overline{c} + c''$, etc. and spatially average

Depth-averaged eqns

Continuity

 $\eta \rightarrow$

$$\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} (\overline{\overline{u}}H) + \frac{\partial}{\partial y} (\overline{\overline{v}}H) = 0$$

from $\frac{\partial w}{\partial z}$ + kinematic surface bc of $\frac{\partial u}{\partial x}, \frac{\partial v}{\partial y}$

Mass and Momentum straight forward except for NL terms

$$\int_{-h}^{\eta} \frac{\partial}{\partial x} (u^2) dz = \frac{\partial}{\partial x} \int \left(\overline{\overline{u}} + u''\right) \left(\overline{\overline{u}} + u''\right) dz = \frac{\partial}{\partial x} \int \overline{\overline{u}}^2 dz + 2 \int \overline{\overline{u}} u'' dz + \frac{\partial}{\partial x} \int u''^2 dz$$

$$=\frac{\partial}{\partial x}\left(\overline{\overline{u}}^{2}H\right)+\frac{\partial}{\partial x}\left(\overline{\overline{u''}}^{2}H\right)$$

momentum dispersion

$$\int_{-h}^{O} \frac{\partial}{\partial x} (uc) dz = \frac{\partial}{\partial x} \left(\overline{\overline{u}} \, \overline{\overline{c}} \, H \right) + \frac{\partial}{\partial x} \left(\overline{\overline{u}} \, \overline{c}^{"} H \right)$$

mass dispersion

Depth-averaged eqns, cont'd

x-momentum



Depth-ave Long. dispersion long. diff

Depth integrated eqns, cont'd

Mass Transport



$$\frac{\partial}{\partial x} \left[H \overline{E_x} \frac{\partial c}{\partial x} - \overline{u'' c''} H \right] \qquad \frac{\partial}{\partial y} \left[H \overline{E_y} \frac{\partial c}{\partial y} - \overline{v'' c''} H \right]$$

Depth-ave Long dispersion long. diff

Comments

 ε_L, ε_T, E_L, E_T are longitudinal and transverse momentum and mass shear viscosity/dispersion coefficients.

 $\$ $\epsilon_L >> \epsilon_T$ and $E_L >> E_T$, but relative importance depends on longitudinal gradients

 Dispersion process represented as Fickian (explained shortly)

Boundary Conditions: momentum

$$\frac{\tau_{sx}}{\rho} = C_D \sqrt{U_w^2 + V_w^2} U_w$$

Surface shear stress due to wind (components U_w and V_w); external input (unless coupled air-water model)

Assumes $U_w >> u_s$; $C_D = drag$ coefficient ~ 10⁻³ (more in Ch 8)

$$\frac{\tau_{bx}}{\rho} = C_f \sqrt{\overline{u}^2 + \overline{v}^2} \,\overline{\overline{u}}$$
$$\cong u_*^2$$

Bottom shear stress caused by flow (computed by model)

Different models for C_f (Darcy-Weisbach f; Manning n; Chezy C),

e.g.,
$$\tau_{bx} = \frac{J}{8} \rho \overline{\overline{u}}^2$$

Boundary Conditions: mass transport



Boundary Conditions: mass transport



Magnitude of terms: E₇



$E_z \text{ cont'd}$ $\overline{\overline{E}_z} = 0.07u_*H$

Seen previously; from analogy of mass and momentum conservation (Reynolds' analogy) and log profile for velocity



Transverse mixing: E_{T}

 $\frac{E_T}{u_*H} \cong 0.08 - 0.24$ (say 0.15)

$$\frac{E_T}{u_*H} \cong 0.2 - 4.6$$
 (say 0.6)

 $\tau_{tm} \cong \frac{0.5B^2}{E_T} = \frac{0.5B^2}{0.6u_*H}$

$$x_{tm} = \frac{0.5B^2}{0.6u_*H}\overline{\overline{u}}; \quad if \ \overline{\overline{u}} = 20u_*$$

 $=\frac{17B^2}{H}$

Real channels (irregularities, braiding, secondary circulation)

Laboratory rectangular channels

B = channel width

Example

B = 100 m, H = 5m, u = 1 m/s

$$X_{vm} = 150H = 750 m$$

 $x_{tm} = 17B^2/H = (17)(100)^2/5 = 34,000 m$ (34 km)

It may take quite a while before concentrations can be considered laterally (transversally) uniform

Simplifications

Steady state; depth-averaged; no lateral advection or long dispersion; no boundary fluxes

$$\frac{\partial}{\partial t} \left(\overline{c}H\right) + \frac{\partial}{\partial x} \left(\overline{u} \,\overline{c}H\right) + \frac{\partial}{\partial y} \left(\overline{v} \,\overline{c}H\right) = \frac{\partial}{\partial x} \left[HE_L \frac{\partial\overline{c}}{\partial x}\right] + \frac{\partial}{\partial y} \left[HE_T \frac{\partial\overline{c}}{\partial y}\right] + E_z \frac{\partial c}{\partial z}\Big|_s - E_z \frac{\partial c}{\partial z}\Big|_b$$
$$H\overline{u} \frac{\partial\overline{c}}{\partial x} = \frac{\partial}{\partial y} \left(HE_T \frac{\partial c}{\partial y}\right)$$

Uniform channel





A useful extension: cumulative discharge approach (Yotsukura & Sayre, 1976)

Use cumulative discharge (Q_c) instead of y as lateral variable



Longitudinal Shear Dispersion

Why is longitudinal dispersion Fickian?

Original analysis by Taylor (1953, 1954) for flow in pipes; following for 2D flow after Elder (1959)



Longitudinal Shear dispersion

Why is longitudinal dispersion Fickian?

Original analysis by Taylor (1953, 1954) for flow in pipes; following for 2D flow after Elder (1959)







a) $L \gg H \implies \text{longitudinal dispersion} \ll \text{vertical} \qquad 5, 6 \ll 7$ b) $\overline{c} \gg c" \implies \partial c'' / \partial \zeta \ll \partial \overline{c} / \partial \zeta \qquad 4 \ll 3$ c) $x \gg L \implies \partial / \partial \tau \ll u'' \partial / \partial \zeta \qquad 1, 2 \ll 3$ $\frac{\partial \overline{c}}{\partial \tau} + \frac{\partial c''}{\partial \tau} + u'' \frac{\partial \overline{c}}{\partial \zeta} + u'' \frac{\partial c''}{\partial \zeta} = \frac{\partial}{\partial \zeta} \left(E_x \frac{\partial \overline{c}}{\partial \zeta} \right) + \frac{\partial}{\partial \zeta} \left(E_y \frac{\partial c''}{\partial \zeta} \right) + \frac{\partial}{\partial z} \left(E_z \frac{\partial c''}{\partial z} \right)$

2 3 4 5



Integrate over z twice to get c"; multiply by u"; integrate again and divide by H (depth average); add minus sign



Use E_L to compute σ_L or use measured σ_L to deduce E_L

Comments

 E_L involves differential advection (u")
 with transverse mixing in direction of advection gradient (E_z)

E_L ~ 1/E_z; perhaps counter-intuitive, but look at time scales:



A thought experiment

Consider the trip on the Mass Turnpike from Boston to the NY border (~150 miles).

Assume two lanes in each direction, and that cars in left lane always travel 65 mph, while those in the right lane travel 55 mph.

At the start 50 cars in each lane have their tops painted red and a helicopter observes the "dispersion" in their position as they travel to NY

1) How does this dispersion depend on the frequency of lane changes?

2) Would dispersion increase or decrease if there were a third (middle) lane where cars traveled at 60 mph?

Thought experiment, cont'd



What are the analogs of H, E_z and u"

Thought experiment, cont'd



- H ~ number of lanes
- $E_z \sim$ frequency of lane changing
- $u^{\prime\prime}$ ~ difference between average and lane-specific speed
- 1) Decreasing E_z increases dispersion (as long as there is some E_z)
- 2) Increasing lanes increases H, decreases mean square u",

$$\overline{(u'')^2} = \frac{(65-60)^2 + (55-60)^2}{2} = 50/2$$
 (2 lanes)
$$\overline{(u'')^2} = \frac{(65-60)^2 + (60-60)^2 + (55-60)^2}{3} = 50/3$$
 (3 lanes)

If E_z is constant, net effect is increase in E_L by $(3/2)^2(2/3) = 50\%$

1D (river) dispersion

$$u = \overline{\overline{u}} + u"; \quad c = \overline{\overline{c}} + c"$$

 $c = \frac{1}{A} \int_{A} c dA$ Insert into GE and spatial average

Continuity

$$\frac{\partial A}{\partial t} + \frac{\partial}{\partial x}(Au) = q_L \qquad q_L = \text{lateral inflow/length [L^2/T]}$$

Mass Conservation (conservative form)

$$\frac{\partial}{\partial t}(Ac) + \frac{\partial}{\partial x}(Auc) = \frac{\partial}{\partial x} \left[A\overline{E_x} \frac{\partial c}{\partial x} - A\overline{u''c''} \right] + Ar_i + q_L c_L$$
$$AE_L \frac{\partial c}{\partial x} \quad \text{Longitudinal dispersion again}$$

1D (river) dispersion, cont'd

NC form from conservative equation minus c times continuity

$$\frac{\partial}{\partial t}(Ac) + \frac{\partial}{\partial x}(Auc) = \frac{\partial}{\partial x} \left[A\overline{E_x} \frac{\partial c}{\partial x} - A\overline{u''c''} \right] + Ar_i + q_L c_L$$
$$- c \cdot \left\{ \frac{\partial A}{\partial t} + \frac{\partial}{\partial x}(Au) = q_L \right\}$$

Mass Conservation (NC form)

$$\frac{\partial c}{\partial t} + u \frac{\partial c}{\partial x} = \frac{1}{A} \frac{\partial}{\partial x} \left(A E_L \frac{\partial c}{\partial x} \right) + r_i + \frac{q_L}{A} \left(c_L - c \right)$$

Note: if c_L > c, c increases; if c_L < c, c decreases (dilution)

E_L for rivers

Elder formula accounts for vertical shear (OK for depth averaged models that resolve lateral shear); here we need to parameterize lateral and vertical shear. Analysis by Fischer (1967)

$$-\overline{\overline{u''c''}} = I_b \frac{B^2}{E_T} \overline{\overline{u''}}^2 \frac{\partial \overline{\overline{c}}}{\partial x} \qquad B = \text{river width}$$

$$E_T = \text{transverse dispersion coefficient}$$

$$I_b - \text{ND triple integration (across A)} \sim 0.07$$

Same form as Elder, but now time scale is B^2/E_T , rather than H^2/E_z . $E_T > E_z$, but $B^2 >> H^2 =>$ this E_L is generally much larger

E_L for rivers, cont'd

Using approximations for u'', E_T , etc.



$$\frac{E_L}{u_*H} \cong 4 \left(\frac{B}{H}\right)^2$$

Magnitude of terms, revisited



Previous Example, revisited

 $B = 100 m, H = 5m, u = 1 m/s, u_* = 0.05u = 0.05$



 $\frac{d}{dt}\sigma_x^2 = 2E_L \qquad => \text{Gaussian Distribution; but only} \\ \text{after cross-sectional mixing}$

 $x_{tm} = \frac{0.5B^2}{E_T}u$

x_{tm} = 34 km if point source on river bank;



X_{tm}

Previous Example, revisited

 $B = 100 \text{ m}, H = 5 \text{m}, u = 1 \text{ m/s}, u_* = 0.05 \text{u} = 0.05$

 $E_L = \frac{0.01u^2 B^2}{u_* H} = \frac{(0.01)(1)^2 (100)^2}{(0.05)(5)} = 400 \text{ m}^2/\text{s}$

 $\frac{d}{dt}\sigma_x^2 = 2E_L \qquad => \text{Gaussian Distribution; but only} \\ \text{after cross-sectional mixing}$

 $x_{tm} = \frac{0.5B^2}{E_T}u$

4 times less if point source in mid-stream



X_{tm}

Previous Example, revisited

 $B = 100 \text{ m}, H = 5 \text{m}, u = 1 \text{ m/s}, u_* = 0.05 \text{u} = 0.05$



 $\frac{d}{dt}\sigma_x^2 = 2E_L \qquad => \text{Gaussian Distribution; but only} \\ \text{after cross-sectional mixing}$



Less still if distributed across channel (but not zero)



X_{tm}

Storage zones

Real channels often have backwater (storage) zones that increase dispersion and give long tails to c(t) distribution



Storage zones, cont'd



A(x) = cross-sectional area of main channel

 A_s = cross-sectional area of storage zone

 α = storage zone coefficient (rate, t⁻¹; like q_L/A)

If you multiply 1) by A and 2) by A_s , the exchange terms are $\alpha A(c_s-c)$ and $-\alpha A(c_s-c)$

Really the same process as longitudinal dispersion, but instead of cars in either fast or slow lane, some are in the rest stop.