## Introduction to Transportation Systems

## PART III:

TRAVELER TRANSPORTATION

## Chapter 27:

## Deterministic Queuing

# Deterministic Queuing Applied to Traffic Lights 

- Here we introduce the concept of deterministic queuing at an introductory level and then apply this concept to setting of traffic lights.


## Deterministic Queuing

## Deterministic Queuing

In the first situation, we consider $\lambda(\mathrm{t})$, the arrival rate, and $\mu(\mathrm{t})$, the departure rate, as deterministic.

## Deterministic Arrival and Departure Rates



## Deterministic Queuing



## Queuing Diagram



## Another Case

- Now, the numbers were selected to make this simple; at the end of four hours the system is empty. The queue dissipated exactly at the end of four hours. But for example, suppose vehicles arrive at the rate of 1,250 /hour from $t=3$ to $t=4$.


## Another Queuing Diagram

Cumulative
Arrivals


## CLASS DISCUSSION

- What is the longest queue in this system?
-What is the longest individual waiting time?


## Computing Total Delay

Area Between Input and Output Curves


## Choosing Capacity

$$
\begin{aligned}
& \mu(t)=2000 \\
& \mu(t)=1500 \\
& \mu(t)=500
\end{aligned}
$$

## CLASS DISCUSSION

## A Traffic Light as a Deterministic Queue

## Service Rate and Arrival Rate at Traffic Light




## Queuing Diagram per Traffic Light



## Queue Stability

All the traffic must be dissipated during the green cycle.

$$
\begin{aligned}
& \text { If } R+G=C \text { (the cycle time), } \\
& \text { then } \lambda\left(R+t_{0}\right)=\mu t_{0} \text {. } \\
& \text { Rearranging } t_{0}=\frac{\lambda R}{\mu-\lambda}
\end{aligned}
$$

If we define $\frac{\lambda}{\mu}=\rho$ (the "traffic intensity"),
Then $t_{0}=\frac{\rho R}{1-\rho}$
For stability $t_{0} \leq G=C-R$.

# Delay at a Traffic Signal -Considering One Direction 

$$
D=\frac{\lambda R^{2}}{2(1-\rho)}
$$

The total delay per cycle is d

$$
d=\frac{D}{\lambda C}=\frac{R^{2}}{2 C(1-\rho)}
$$

## Two Direction Analysis of Traffic Light

Flows in East-West and North-South Directions


Figure 27.7

$$
\begin{aligned}
& D_{1}=\frac{\lambda_{1} R_{1}{ }^{2}}{2\left(1-\rho_{1}\right)} \\
& \text { where } \rho_{1}=\frac{\lambda_{1}}{\mu}
\end{aligned}
$$

We can write similar expressions for $D_{2}, D_{3}, D_{4}$. We want to minimize $D_{T}$, the total delay, where

$$
D_{T}=D_{1}+D_{2}+D_{3}+D_{4}
$$

## Choosing an Optimum

Remembering that

$$
\begin{aligned}
& R_{2}=R_{1} \\
& R_{4}=R_{3}=\left(C-R_{1}\right)
\end{aligned}
$$

we want to minimize $D_{T}$ where

$$
D_{T}=\frac{\lambda_{1} R_{1}{ }^{2}}{2\left(1-\rho_{1}\right)}+\frac{\lambda_{2} R_{1}{ }^{2}}{2\left(1-\rho_{2}\right)}+\frac{\lambda_{3}\left(C-R_{1}\right)^{2}}{2\left(1-\rho_{3}\right)}+\frac{\lambda_{4}\left(C-R_{1}\right)^{2}}{2\left(1-\rho_{4}\right)}
$$

To obtain the optimal $R_{1}$, we differentiate the expression for total delay with respect to $R_{1}$ (the only unknown) and set that equal to zero.

$$
\frac{d D_{T}}{d R_{1}}=\frac{\lambda_{1} R_{1}}{1-\rho_{1}}+\frac{\lambda_{2} R_{1}}{1-\rho_{2}}-\frac{\lambda_{3}\left(C-R_{1}\right)}{1-\rho_{3}}-\frac{\lambda_{4}\left(C-R_{1}\right)}{1-\rho_{4}}=0
$$

## Try a Special Case

$$
\lambda_{1}=\lambda_{2}=\lambda_{3}=\lambda_{4}
$$

Therefore, $\rho_{1}=\rho_{2}=\rho_{3}=\rho_{4}$.
The result, then, is

$$
R_{1}=\frac{C}{2}, R_{3}=\frac{C}{2}
$$

This makes sense. If the flows are equal, we would expect the optimal design choice is to split the cycle in half in the two directions.

The text goes through some further mathematical derivations of other cases for the interested student.

