1.010 Uncertainty in Engineering Fall 2008

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## 1.010 - Brief Notes #4 Random Vectors

A set of 2 or more random variables constitutes a random vector. For example, a random vector with two components,  $\underline{X} = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$ , is a function from the sample space of an experiment to the (x<sub>1</sub>, x<sub>2</sub>) plane.

## Discrete Random Vectors

• Characterization

• Joint PMF of X<sub>1</sub> and X<sub>2</sub>:  

$$P_{\underline{X}}(\underline{x}) = P_{X_1,X_2}(x_1,x_2) = P[(X_1 = x_1) \cap (X_2 = x_2)]$$

• *Joint CDF of* X<sub>1</sub> *and* X<sub>2</sub>:

$$\begin{split} F_{\underline{X}}(\underline{x}) &= F_{X_1, X_2}(x_1, x_2) = P[(X_1 \le x_1) \cap (X_2 \le x_2)] \\ &= \sum_{u_1 \le x_1} \sum_{u_2 \le x_2} P_{X_1, X_2}(u_1, u_2) \end{split}$$

• <u>Marginal Distribution</u>

• *Marginal PMF of* X<sub>1</sub>:

$$P_{X_1}(X_1) = P[X_1 = X_1] = \sum_{\text{all } X_2} P[(X_1 = X_1) \cap (X_2 = X_2)] = \sum_{\text{all } X_2} P_{X_1, X_2}(X_1, X_2)$$

• *Marginal CDF of* X<sub>1</sub>:

$$F_{X_1}(x_1) = P[X_1 \le x_1] = P[(X_1 \le x_1) \cap (X_2 < \infty)] = F_{X_1, X_2}(x_1, \infty) = \sum_{\text{all } x_2} \sum_{u \le x_1} P_{X_1, X_2}(u, x_2)$$

## • Continuous Random Vectors

- <u>Characterization</u>
  - Joint CDF  $F_{X_1,X_2}(x_1,x_2)$ : same as for discrete vectors.
  - Joint Probability Density Function (JPDF) of  $\underline{X} = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$ ,  $f_{X_1,X_2}(X_1,X_2)$ : This function is defined such that:

This function is defined such that:

 $f_{X_1,X_2}(x_1,x_2)dx_1dx_2 = P[(x_1 \le X_1 < x_1 + dx_1) \cap (x_2 \le X_2 < x_2 + dx_2)]$ 

Relationships between  $f_{X_1,X_2}$  and  $F_{X_1,X_2}$ :

$$f_{X_{1},X_{2}}(x_{1},x_{2}) = \frac{\partial^{2} F_{X_{1},X_{2}}(x_{1},x_{2})}{\partial x_{1} \partial x_{2}}$$
$$F_{X_{1},X_{2}}(x_{1},x_{2}) = \int_{-\infty}^{x_{1}} \int_{-\infty}^{x_{2}} f_{X_{1},X_{2}}(u_{1},u_{2}) du_{1} du_{2}$$

• <u>Marginal distribution of X1</u>

• *CDF*: 
$$F_{X_1}(x_1) = F_{X_1,X_2}(x_1,\infty)$$

• PDF: 
$$f_{X_{1}}(x_{1}) = \frac{dF_{X_{1}}(x_{1})}{dx_{1}} = \frac{\partial F_{X_{1},X_{2}}(x_{1},\infty)}{\partial x_{1}}$$
$$= \frac{\partial}{\partial x_{1}} \left( \int_{-\infty}^{x_{1}} du_{1} \int_{-\infty}^{\infty} f_{X_{1},X_{2}}(u_{1},u_{2}) du_{2} \right)$$
$$= \int_{-\infty}^{\infty} f_{X_{1},X_{2}}(x_{1},u_{2}) du_{2}$$

• <u>Conditional PDF of</u>  $(X_1 | X_2 = x_2)$   $f_{(X_1|X_2=x_2)}(x_1) = \frac{f_{X_1,X_2}(x_1,x_2)}{f_{X_2}(x_2)}$  $\propto f_{X_1,X_2}(x_1,x_2), \text{ for } f_{X_2}(x_2) \neq 0$  • <u>Conditional Distribution</u>

• Conditional PMF of 
$$(X_1 | X_2 = x_2)$$
:

$$P_{(X_1|X_2=x_2)}(x_1) = P[X_1 = x_1 | X_2 = x_2] = \frac{P_{X_1,X_2}(x_1, x_2)}{P_{X_2}(x_2)}$$
  

$$\propto P_{X_1,X_2}(x_1, x_2)$$



Example of discrete joint distribution: joint PMF of traffic at remote location (X in cars/30 sec. interval) and traffic recorded by some imperfect traffic counter (Y) (note: X and Y are the random variables X<sub>1</sub> and X<sub>2</sub> in our notation).



Example of discrete joint distribution: marginal distributions. (a) Marginal PMF of actual traffic X, and (b) marginal counter response Y.

## • Independent Random Variables

X1 and X2 are independent variables if:

$$F_{X_1,X_2}(x_1,x_2) = F_{X_1}(x_1) \cdot F_{X_2}(x_2)$$

Equivalent conditions for continuous random vectors are:

$$f_{X_1,X_2}(x_1,x_2) = f_{X_1}(x_1) \cdot f_{X_2}(x_2)$$
  
or:  
$$f_{(X_1|X_2=x_2)}(x_1) = f_{X_1}(x_1)$$

and for discrete random vectors:

$$P_{X_1,X_2}(x_1,x_2) = P_{X_1}(x_1) \cdot P_{X_2}(x_2)$$
  
or:  
$$P_{(X_1|X_2=x_2)}(x_1) = P_{X_1}(x_1)$$



Example of continuous joint distribution: joint and marginal PMF of random variables X and Y. (Note: X and Y are the random variables X<sub>1</sub> and X<sub>2</sub> in our notation)