1.3.2 Multiplication of Matrices/Matrix Transpose

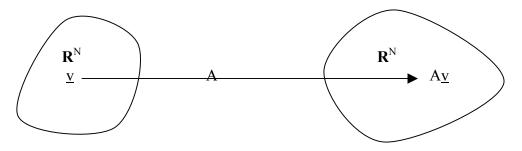
In section 1.3.1, we considered only square matrices, as these are of interest in solving linear problems $A\underline{x} = \underline{b}$.

The interpretation of a matrix as a linear transformation can be extended to non-square matrix. If we consider a M x N real matrix A, then A maps every vector $\underline{v} \in \mathbf{R}^N$ into a vector (now of dimensions m, not N) $A \underline{v} \in \mathbf{R}^N$, according to the rule

$$\mathbf{A}\underline{\mathbf{v}} = \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \dots & \mathbf{a}_{1N} \\ \mathbf{a}_{21} & \mathbf{a}_{22} & \dots & \mathbf{a}_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{a}_{m1} & \mathbf{a}_{m2} & \dots & \mathbf{a}_{mN} \end{bmatrix} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_{12} \\ \vdots \\ \mathbf{v}_N \end{bmatrix} = \begin{bmatrix} \mathbf{a}_{11}\mathbf{v}_1 + \mathbf{a}_{12}\mathbf{v}_2 + \dots + \mathbf{a}_{1N}\mathbf{v}_N \\ \mathbf{a}_{21}\mathbf{v}_1 + \mathbf{a}_{22}\mathbf{v}_2 + \dots + \mathbf{a}_{2N}\mathbf{v}_N \\ \vdots \\ \mathbf{a}_{m1}\mathbf{v}_1 + \mathbf{a}_{m2}\mathbf{v}_2 + \dots + \mathbf{a}_{mN}\mathbf{v}_N \end{bmatrix}$$
(1.3.2-1)

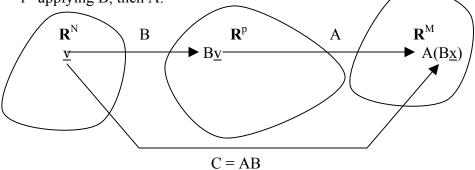
Note that the product A<u>v</u> is defined only if the number of columns of A equals the dimensions (# of components) of <u>v</u>.

We give the M x N matrix A, with all a_{ij} real, the following pictorial interpretation:



The interpretation of non-square matrices as linear transformations provides the following rule for multiplying two real matrices:

Let A be a M x P real matrix, and let B be a P x N real matrix. We define C = AB to be the M x N matrix (also real) that performs the same transformation to a vector $\underline{v} \in \mathbf{R}^{N}$ as 1^{st} applying B, then A.



First, to $\underline{\mathbf{v}} \in \mathbf{R}^{N}$ we apply B,

$$\mathbf{B}\underline{\mathbf{v}} = \begin{bmatrix} \mathbf{b}_{11} & \mathbf{b}_{12} & \dots & \mathbf{b}_{1N} \\ \mathbf{b}_{21} & \mathbf{b}_{22} & \dots & \mathbf{b}_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{b}_{p1} & \mathbf{b}_{p2} & \dots & \mathbf{b}_{pN} \end{bmatrix} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_{12} \\ \vdots \\ \mathbf{v}_N \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^N b_{1j} \mathbf{v}_j \\ \sum_{j=1}^N b_{2j} \mathbf{v}_j \\ \vdots \\ \sum_{j=1}^N b_{pj} \mathbf{v}_j \end{bmatrix}$$
(1.3.2-2)

We then apply A to $B\underline{v} \in \mathbf{R}^{p}$,

$$A(B\underline{v}) = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1p} \\ a_{21} & a_{22} & \dots & a_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mp} \end{bmatrix} \begin{bmatrix} \sum_{j=1}^{N} b_{1j} v_j \\ \sum_{j=1}^{N} b_{2j} v_j \\ \vdots \\ \sum_{j=1}^{N} b_{pj} v_j \end{bmatrix} = \begin{bmatrix} \sum_{k=1}^{p} a_{1k} \sum_{j=1}^{N} b_{kj} v_j \\ \sum_{k=1}^{p} a_{2k} \sum_{j=1}^{N} b_{kj} v_j \\ \vdots \\ \sum_{k=1}^{p} a_{mk} \sum_{j=1}^{N} b_{kj} v_j \end{bmatrix}$$
(1.3.2-3)

If we compare to

$$C\underline{\mathbf{v}} = \begin{bmatrix} \mathbf{c}_{11} & \mathbf{c}_{12} & \dots & \mathbf{c}_{1N} \\ \mathbf{c}_{21} & \mathbf{c}_{22} & \dots & \mathbf{c}_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{c}_{m1} & \mathbf{c}_{m2} & \dots & \mathbf{c}_{mN} \end{bmatrix} \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_{12} \\ \vdots \\ \mathbf{v}_N \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^N c_{1j} \mathbf{v}_j \\ \sum_{j=1}^N c_{2j} \mathbf{v}_j \\ \vdots \\ \sum_{j=1}^N c_{mj} \mathbf{v}_j \end{bmatrix}$$
(1.3.2-4)

We see that rearranging (1.3.2-2) yields

$$A(B\underline{v}) = \begin{bmatrix} \sum_{j=1}^{N} \left(\sum_{k=1}^{p} a_{1k} b_{kj} \right) v_{j} \\ \sum_{j=1}^{N} \left(\sum_{k=1}^{p} a_{2k} b_{kj} \right) v_{j} \\ \vdots \\ \sum_{j=1}^{N} \left(\sum_{k=1}^{p} a_{mk} b_{kj} \right) v_{j} \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^{N} c_{1j} v_{j} \\ \sum_{j=1}^{N} c_{2j} v_{j} \\ \vdots \\ \sum_{j=1}^{N} c_{mj} v_{j} \end{bmatrix}$$
(1.3.2-5)

The (i,j) element of the matrix C = AB is therefore

$$C_{ij} = \sum_{k=1}^{p} a_{ik} b_{kj}$$
 (1.3.2-6)

We compute this element by summing the product of elements A along row #I from left \rightarrow right with those elements of B in column #j from top \rightarrow bottom.

$$AB = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1p} \\ a_{21} & a_{22} & \dots & a_{2p} \\ & & \stackrel{\rightarrow}{a} \\ i_1 & a_{i2} & \dots & a_{ip} \\ \vdots & & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mp} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1j} & \dots & b_{1N} \\ b_{21} & b_{22} & \dots & b_{2j} & \dots & b_{2N} \\ \vdots & & & \vdots & & \vdots \\ b_{p1} & b_{p2} & \dots & b_{pj} & \dots & b_{pN} \end{bmatrix} \\ = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} row \#i \\ \vdots \\ column \# j \\ (1.3.2-7) \\ column \# j$$

row # i

We note that the product of two matrices A and B, C = AB, is defined only if the number of columns of A equals the number of rows of B.

Note also that in general AB \neq BA (1.3.2-8). We define the <u>commutator</u> of A and B as $[A,B] \equiv A B - BA$ (1.3.2-9)

Note that we can interpret our rule for multiplying a vector $\underline{v} \in \mathbf{R}^N$ by an M x N matrix A by considering \underline{v} to be a matrix of dimension N x 1, i.e. a <u>column vector</u>.

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1N} \\ a_{21} & a_{22} & \dots & a_{2N} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mN} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_N \end{bmatrix} = \begin{bmatrix} \sum_{k=1}^N a_{1k} v_k \\ \sum_{k=1}^N a_{2k} v_k \\ \vdots \\ \sum_{k=1}^N a_{mk} v_k \end{bmatrix}$$
(1.3.2-10)

This is the convention that we will use. We can also write \underline{v} as a row vector by taking the transpose,

$$\underline{\mathbf{v}}^{\mathrm{T}} = [\mathbf{v}_1 \ \mathbf{v}_2 \ \dots \ \mathbf{v}_{\mathrm{N}}]$$
 (1.3.2-11)

We see that \underline{v}^{T} is a 1 x N matrix. The dot product $\underline{v} \bullet \underline{w}$ can therefore be written for $\underline{v}, \underline{w} \in \mathbf{R}^{N}$

$$\underline{v} \bullet \underline{w} = \underline{v}^{\mathrm{T}} \underline{w} = \begin{bmatrix} v_1 & v_2 & \dots & v_N \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_N \end{bmatrix} = v_1 w_1 + v_2 w_2 + \dots + v_N w_N \quad (1.3.2-12)$$

We define a matrix transpose operation on a real matrix A of M rows and N columns as

$$\mathbf{A}^{\mathrm{T}} = \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \mathbf{a}_{13} & \dots & \mathbf{a}_{1N} \\ \mathbf{a}_{21} & \mathbf{a}_{22} & \mathbf{a}_{23} & \dots & \mathbf{a}_{2N} \\ \vdots & \vdots & \vdots & \vdots \\ \mathbf{a}_{m1} & \mathbf{a}_{m2} & \mathbf{a}_{m3} & \dots & \mathbf{a}_{mN} \end{bmatrix}^{\mathrm{T}} = \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{21} & \dots & \mathbf{a}_{m1} \\ \mathbf{a}_{12} & \mathbf{a}_{22} & \dots & \mathbf{a}_{m2} \\ \mathbf{a}_{13} & \mathbf{a}_{23} & \dots & \mathbf{a}_{m3} \\ \vdots & \vdots & \vdots \\ \mathbf{a}_{1N} & \mathbf{a}_{2N} & \dots & \mathbf{a}_{mN} \end{bmatrix}$$
(1.3.2-13)

If A is an M x N matrix, A^T is N x M and $(A^T)_{ij} = a_{ji}$ (1.3.2-14)