# 16.21 Techniques of Structural Analysis and Design Spring 2005 Unit \#1 

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In this course we are going to focus on energy and variational methods for structural analysis. To understand the overall approach we start by contrasting it with the alternative vector mechanics approach:

## Example of Vector mechanics formulation:

Consider a simply supported beam subjected to a uniformly-distributed load $q_{0}$, (see Fig.1). To analyze the equilibrium of the beam we consider the free body diagram of an element of length $\Delta x$ as shown in the figure and apply Newton's second law:

$$
\begin{gather*}
\sum F_{y}=0: V-q_{0} \Delta x-(V+\Delta V)=0  \tag{1}\\
\sum M_{B}=0:-V \Delta x-M+(M+\Delta M)+\left(q_{0} \Delta x\right) \frac{\Delta x}{2}=0 \tag{2}
\end{gather*}
$$

Dividing by $\Delta x$ and taking the limit $\Delta x \rightarrow 0$ :

$$
\begin{gather*}
\frac{d V}{d x}=-q_{0}  \tag{3}\\
\frac{d M}{d x}=V \tag{4}
\end{gather*}
$$



Figure 1: Equilibrium of a simply supported beam

Eliminating $V$, we obtain:

$$
\begin{equation*}
\frac{d^{2} M}{d x^{2}}+q_{0}=0 \tag{5}
\end{equation*}
$$

Recall from Unified Engineering or 16.20 (we'll cover this later in the course also) that the bending moment is related to the deflection of the beam $w(x)$ by the equation:

$$
\begin{equation*}
M=E I \frac{d^{2} w}{d x^{2}} \tag{6}
\end{equation*}
$$

where $E$ is the Young's modulus and $I$ is the moment of inertia of the beam. Combining 5 and 6 , we obtain:

$$
\begin{equation*}
\frac{d^{2}}{d x^{2}}\left(E I \frac{d^{2} w}{d x^{2}}\right)+q_{0}=0, \quad 0<x<L \tag{7}
\end{equation*}
$$

The boundary conditions of the beam are:

$$
\begin{equation*}
w(0)=w(L)=0, \quad M(0)=M(L)=0 \tag{8}
\end{equation*}
$$

The solution of equations 7 and 8 is given by:

$$
\begin{equation*}
w(x)=-\frac{q_{0}}{24 E I} x(L-x)\left(L^{2}+L x-x^{2}\right) \tag{9}
\end{equation*}
$$

## Corresponding variational formulation

The same problem can be formulated in variational form by introducing the potential energy of the beam system:

$$
\begin{equation*}
\Pi(w)=\int_{0}^{L}\left[\frac{E I}{2}\left(\frac{d^{2} w}{d x^{2}}\right)^{2}+q_{0} w\right] d x \tag{10}
\end{equation*}
$$

and requiring that the solution $w(x)$ be the function minimizing it that also satisfies the displacement boundary conditions:

$$
\begin{equation*}
w(0)=w(L)=0 \tag{11}
\end{equation*}
$$

A particularly attractive use of the variational formulation lies in the determination of approximate solutions. Let's seek an approximate solution to the previous beam example of the form:

$$
\begin{equation*}
w_{1}(x)=c_{1} x(L-x) \tag{12}
\end{equation*}
$$

which has a continuous second derivative and satisfies the boundary conditions 11. Substituting $w_{1}(x)$ in 10 we obtain:

$$
\begin{align*}
\Pi\left(c_{1}\right) & =\int_{0}^{L}\left[\frac{E I}{2}\left(-2 c_{1}\right)^{2}+q_{0} c_{1}\left(L x-x^{2}\right)\right] d x  \tag{13}\\
& =2 E I L c_{1}^{2}+\frac{L^{3}}{6} q_{0} c_{1}
\end{align*}
$$

Note that our functional $\Pi$ now depends on $c_{1}$ only. $w_{1}(x)$ is an approximate solution to our problem if $c_{1}$ minimizes $\Pi=\Pi\left(c_{1}\right)$. A necessary condition for this is:

$$
\frac{d \Pi}{d c_{1}}=4 E I L c_{1}+q_{0} \frac{L^{3}}{6}=0
$$

or $c_{1}=-\frac{q_{0} L^{2}}{24 E I}$, and the approximate solution becomes:

$$
w_{1}(x)=-\frac{q_{0} L^{2}}{24 E I} x(L-x)
$$

In order to assess the accuracy of our approximate solution, let's compute the approximate deflection of the beam at the midpoint $\delta_{1}=w_{1}\left(\frac{L}{2}\right)$ :

$$
\delta=-\frac{q_{0} L^{2}}{24 E I}\left(\frac{L}{2}\right)^{2}=-\frac{q_{0} L^{4}}{96 E I}
$$

The exact value $\delta=w\left(\frac{L}{2}\right)$ is obtained from eqn. 9 as:

$$
\delta=-\frac{q_{0}}{24 E I} \frac{L}{2}\left(L-\frac{L}{2}\right)\left[L^{2}+L \frac{L}{2}-\left(\frac{L}{2}\right)^{2}\right]=-\frac{5}{384} \frac{q_{0} L^{4}}{E I}
$$

We observe that:

$$
\frac{\delta_{1}}{\delta}=\frac{\frac{1}{96}}{\frac{5}{384}}=\frac{4}{5}=0.8
$$

i.e. the approximate solution underpredicts the maximum deflection by $20 \%$.

However, if we consider the following approximation with 3 degrees of freedom (note it also satisfies the essential boundary conditions, eqn.11):

$$
\begin{equation*}
w_{3}(x)=c_{1} x(L-x)+c_{2} x^{2}(L-x)+c_{3} x^{3}(L-x) \tag{14}
\end{equation*}
$$

and require that $\Pi\left(c_{1}, c_{2}, c_{3}\right)$ be a minimum:

$$
\frac{\partial \Pi}{\partial c_{1}}=0, \frac{\partial \Pi}{\partial c_{2}}=0, \frac{\partial \Pi}{\partial c_{3}}=0
$$

i.e.:

$$
\begin{aligned}
& 4 c 1 E I L+2 c 2 E I L^{2}+2 c 3 E I L^{3}+\frac{L^{3} q 0}{6}=0 \\
& 2 c 1 E I L^{2}+4 c 2 E I L^{3}+4 c 3 E I L^{4}+\frac{L^{4} q 0}{12}=0 \\
& 2 c 1 E I L^{3}+4 c 2 E I L^{4}+\frac{24 c 3 E I L^{5}}{5}+\frac{L^{5} q 0}{20}=0
\end{aligned}
$$

whose solution is:

$$
c 1 \rightarrow \frac{-\left(L^{2} q 0\right)}{24 E I}, c 2 \rightarrow \frac{-(L q 0)}{24 E I}, c 3 \rightarrow \frac{q 0}{24 E I}
$$

If you replace this values in eqn. 14 and evaluate the deflection at the midpoint of the beam you obtain the exact solution !!!

